

# Automatic Differentiation of Functional Programs or Lambda the Ultimate Calculus

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Purdue University

Lecture Circuit 2009

Part of this talk covers joint work with Barak A. Pearlmutter.

# The Essence

```
(define (f x) 2x3)
```

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```
(define (f x) 2x3)      ~~~ (define (f' x) 6x2)
```

# The Essence

```
(define (g x) (sinf(x)))
```

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(define (g x) (sin f(x)) ~> (define (g' x) (f'(x) cos f(x)))
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(D g)                  => (D ⟨{f ↪ λx 2x3}, λx sinf(x)⟩)
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(`map-closure`  
*f*  $\langle \{x_1 \mapsto v_1, \dots\}, e \rangle$ )  $\implies \langle \{x_1 \mapsto f(v_1), \dots\}, e \rangle$

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need reflective transformation of closure bodies

# The Essence

$$\begin{aligned} (\text{define } (f \ x) \ 2x^3) &\rightsquigarrow (\text{define } (f' \ x) \ 6x^2) \\ (\text{define } (g \ x) \ \sin f(x)) &\rightsquigarrow (\text{define } (g' \ x) \ f'(x) \cos f(x)) \\ (\mathcal{D} \ g) &\implies (\mathcal{D} \ \langle \{f \mapsto \lambda x \ 2x^3\}, \lambda x \ \sin f(x) \rangle) \\ &\implies \langle \{f \mapsto \lambda x \ 2x^3, f' \mapsto \lambda x \ 6x^2\}, \\ &\quad \lambda x f'(x) \cos f(x) \rangle \\ (\text{map-closure } f \ \langle \{x_1 \mapsto v_1, \dots\}, e \rangle) &\implies \langle \{x_1 \mapsto f(v_1), \dots\}, e \rangle \end{aligned}$$

need reflective transformation of closure bodies  
want transformation done at compile time

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need reflective transformation of closure bodies  
want transformation done at compile time  
need flow analysis

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(`define (f x) 2x3`)  $\rightsquigarrow$  (`define (f' x) 6x2`)

(`define (g x) sin f(x)`)  $\rightsquigarrow$  (`define (g' x) f'(x) cos f(x)`)

( $\mathcal{D}$  `g`)  $\implies$  ( $\mathcal{D}$   $\langle \{f \mapsto \lambda x. 2x^3\}, \lambda x. \sin f(x) \rangle$ )

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(`map-closure f ⟨{x1 ↪ v1, ...}, e⟩`)  $\implies \langle \{x_1 \mapsto f(v_1), \dots\}, e \rangle$

need reflective transformation of closure bodies  
want transformation done at compile time  
need **polyvariant** flow analysis

# Nesting

```
(sqrt (sqrt x))
```

# Nesting

(sqrt (sqrt x))

(D (D f))

# Nesting

(sqrt (sqrt x))

( $\mathcal{D}$  ( $\mathcal{D}$  f))

(map (lambda (x) ...) (map (lambda (y) ...) ...))) ...)

# Nesting

(sqrt (sqrt x))

(D (D f))

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# Nesting

(sqrt (sqrt x))

(D (D f))

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$$\max_x \min_y f(x, y)$$

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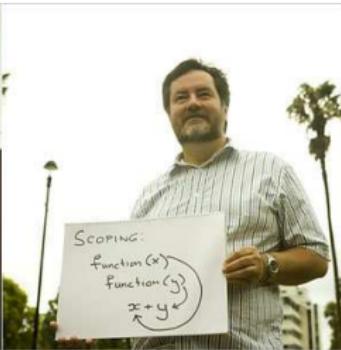
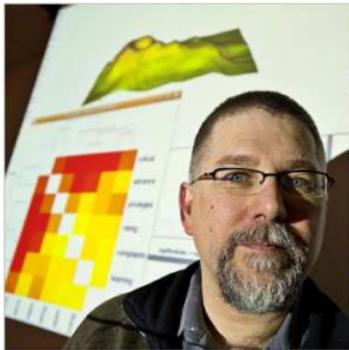
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# The Essence of Forward-Mode AD

$$f(c + \varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!}\varepsilon + \frac{f''(c)}{2!}\varepsilon^2 + \cdots + \frac{f^{(i)}(c)}{i!}\varepsilon^i + \cdots$$

Taylor, B. (1715). *Methodus Incrementorum Directa et Inversa*. London.

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To compute  $\mathcal{D} f c$ :

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$(\mathcal{D} f)$  is  $\mathcal{O}(1)$  relative to  $f$  (both space and time).

# Arithmetic on Complex Numbers

$$a + bi$$

Hamilton, W. R. (1837). *Theory of conjugate functions, or algebraic couples; with a preliminary and elementary essay on algebra as the science of pure time*. Transactions of the Royal Irish Academy, **17**(1):293–422.

# Arithmetic on Complex Numbers

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$$(a_1 + b_1 i) \times (a_2 + b_2 i) = (a_1 \times a_2) + (a_1 \times b_2 + a_2 \times b_1) i + (b_1 \times b_2) i^2$$

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$$\langle a_1, b_1 \rangle + \langle a_2, b_2 \rangle = \langle (a_1 + a_2), (b_1 + b_2) \rangle$$

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# Arithmetic on Dual Numbers

$$x + x'\varepsilon$$
$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$

$$(x_1 + x'_1\varepsilon) \times (x_2 + x'_2\varepsilon) = (x_1 \times x_2) + (x_1 \times x'_2 + x_2 \times x'_1)\varepsilon + (x'_1 + x'_2)\varepsilon^2$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, 4:381–95.

# Arithmetic on Dual Numbers

$$x + x'\varepsilon$$

$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$

$$(x_1 + x'_1\varepsilon) \times (x_2 + x'_2\varepsilon) = (x_1 \times x_2) + (x_1 \times x'_2 + x_2 \times x'_1)\varepsilon + (x'_1 + x'_2)\varepsilon^2$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, 4:381–95.

# Arithmetic on Dual Numbers

$$x + x'\varepsilon$$
$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

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Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, 4:381–95.

# Arithmetic on Dual Numbers

$$x + x'\varepsilon \\ \varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon \\ (x_1 + x'_1\varepsilon) \times (x_2 + x'_2\varepsilon) = (x_1 \times x_2) + (x_1 \times x'_2 + x_2 \times x'_1)\varepsilon$$

$$\langle x, x' \rangle$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, 4:381–95.

# Arithmetic on Dual Numbers

$$x + x'\varepsilon$$
$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$

$$(x_1 + x'_1\varepsilon) \times (x_2 + x'_2\varepsilon) = (x_1 \times x_2) + (x_1 \times x'_2 + x_2 \times x'_1)\varepsilon$$

$$\langle x, x' \rangle$$

$$\langle x_1, x'_1 \rangle + \langle x_2, x'_2 \rangle = \langle (x_1 + x_2), (x'_1 + x'_2) \rangle$$

$$\langle x_1, x'_1 \rangle \times \langle x_2, x'_2 \rangle = \langle (x_1 \times x_2), (x_1 \times x'_2 + x_2 \times x'_1) \rangle$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, 4:381–95.

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))
```

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
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(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x))))
```

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
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      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
```

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
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(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
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    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
```

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
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(define +
  (let ((+ +))
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      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

# Dynamic Overloading: SCMUTILS

```
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(define (primal p) (if (bundle? p) (bundle-primal p) p))
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(define +
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    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
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      (make-bundle (* (primal x1) (primal x2))
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(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

## Convenient

# Dynamic Overloading: SCMUTILS

```
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(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

```
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      (make-bundle (+ (primal x1) (primal x2))
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(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))

(define ((D f) x) (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define ((D f) x)
  (fluid-let ((+ (lambda (x1 x2)
                  (make-bundle (+ (primal x1) (primal x2))
                               (+ (tangent x1) (tangent x2))))))
            (* (lambda (x1 x2)
                  (make-bundle (* (primal x1) (primal x2))
                               (+ (* (primal x1) (tangent x2))
                                  (* (tangent x1) (primal x2)))))))
            (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define ((D f) x)
  (fluid-let ((+ (lambda (x1 x2)
                  (make-bundle (+ (primal x1) (primal x2))
                               (+ (tangent x1) (tangent x2))))))
             (* (lambda (x1 x2)
                  (make-bundle (* (primal x1) (primal x2))
                               (+ (* (primal x1) (tangent x2))
                                  (* (tangent x1) (primal x2)))))))
    (tangent (f (make-bundle x 1)))))

(define (f x) (* 2 (* x (* x x)))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ... ) ...)
```

Convenient but **slow**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

AD\_TOP = f  
AD\_IVARS = x  
AD\_DVARS = f

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)                  AD_TOP = gf
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end

function ggf(x, gx, ggx, gresult, ggresult)
double precision x, gx, ggx, ggf, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gresult = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)                  AD_TOP = gf
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end

function ggf(x, gx, ggx, gresult, ggresult, ggresult)
double precision x, gx, ggx, ggresult, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gresult = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)                 AD_TOP = gf
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end

function ggf(x, gx, gx, ggx, gresult, ggresult)
double precision x, gx, ggx, ggf, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gresult = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)                                AD_TOP = f
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)                  AD_TOP = gf
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end

function ggf(x, gx, ggx, gresult, ggresult, gres)
double precision x, gx, ggx, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gres = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end

function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end

function hgf(x, hx, gx, hgx, gresult, hgresult, hresult)
double precision x, hx, gx, hgx, hgf, hresult, gresult, hgresult
hgf = 2.0d0*x*x*x
hresult = 6.0d0*x*x*hx
gresult = 6.0d0*x*x*gx
hgresult = 6.0d0*x*x*hgx+12.0d0*x*gx*hx
end
```

AD\_TOP = f  
AD\_IVARS = x  
AD\_DVARS = f  
  
AD\_TOP = gf  
AD\_IVARS = x, gx  
AD\_DVARS = gf, gresult  
**AD\_PREFIX = h**

Fast but **inconvenient**

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

## Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

## Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

Slow

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

Slow

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

Slow

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

Slow

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
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```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

Slow and **inconvenient**

# Static Overloading: FADBAD++

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double x;  
... f(x) ...
```

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F<double> f(F<double> x) {return 2*x*x*x;}  
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Slow and **inconvenient**

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```

```
template <typename T>  
T f(T x) {return 2*x*x*x;}  
T x;
```

Slow and **inconvenient**

# Static Overloading: FADBAD++

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double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

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x.diff(0, 1).diff(0,1);  
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Slow and **inconvenient**

# Static Overloading: FADBAD++

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Slow and **inconvenient**

# Our API for Functional Forward AD

Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$

# Our API for Functional Forward AD

$$\text{bundle} : \mathbb{R}^n \times \overline{\mathbb{R}^h} \rightarrow (\mathbb{R}^n \triangleright \overline{\mathbb{R}^h})$$

Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$

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$j^*$  :  $(\mathbb{R}^n \rightarrow \mathbb{R}^m) \rightarrow ((\mathbb{R}^n \triangleright \overline{\mathbb{R}^h}) \rightarrow (\mathbb{R}^m \triangleright \overline{\mathbb{R}^m}))$

Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$   
 $j^*$  maps a **function** to its *push forward*

# Our API for Functional Forward AD

bundle :  $\mathbb{R}^n \times \overline{\mathbb{R}^h} \rightarrow (\mathbb{R}^n \triangleright \overline{\mathbb{R}^h})$   
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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$   
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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$   
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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$   
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Generalize to arbitrary types

# Our API for Functional Forward AD

```
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j*     :  $(\tau_1 \rightarrow \tau_2) \rightarrow ((\tau_1 \triangleright \overline{\tau_1}) \rightarrow (\tau_2 \triangleright \overline{\tau_2}))$ 
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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$   
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Generalize to arbitrary types

What is the tangent of a discrete value or a function?

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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overrightarrow{\mathbb{R}^h}$   
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Generalize to arbitrary types

What is the tangent of a discrete value or a function?

Can abbreviate  $\tau \triangleright \overrightarrow{\tau}$  as  $\overrightarrow{\tau}$

# Our API for Functional Forward AD

$$\begin{aligned}\text{bundle} &: \tau \times \overline{\tau} \rightarrow \overrightarrow{\tau} \\ \text{primal} &: \overrightarrow{\tau} \rightarrow \tau \\ \text{tangent} &: \overrightarrow{\tau} \rightarrow \overline{\tau} \\ j^* &: (\tau_1 \rightarrow \tau_2) \rightarrow (\overrightarrow{\tau_1} \rightarrow \overrightarrow{\tau_2})\end{aligned}$$

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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overrightarrow{\mathbb{R}^n}$   
 $j_*$  maps a function to its *push forward*

Generalize to arbitrary types

What is the tangent of a discrete value or a function?

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Sometimes write  $j_*$  as  $\overrightarrow{\mathcal{J}}$

# Our API for Functional Forward AD

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```
(define ((D f) x) (tangent ((j* f) (bundle x 1))))
```

Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overrightarrow{\mathbb{R}^h}$   
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Generalize to arbitrary types

What is the tangent of a discrete value or a function?

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Convenient

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```
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What is  $(j^* j^*)$ ?

Convenient

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What is  $(j^* j^*)$ ?

Convenient and **fast**

# A property

# A property

$x : \mathbb{R}^n$

# A property

$x : \mathbb{R}^n$

$\overline{x} : \mathbb{R}^n$

# A property

$x : \mathbb{R}^n$

$\overline{x} : \mathbb{R}^n$

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

# A property

$x : \mathbb{R}^n$

$\overline{x} : \mathbb{R}^n$

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$((\mathcal{J} f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]}$$

# A property

$x : \mathbb{R}^n$

$\overline{x} : \mathbb{R}^n$

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$((\mathcal{J} f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]} \quad ((\mathcal{J} f) x) : \mathbb{R}^{m \times n}$$

# A property

$x : \mathbb{R}^n$

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$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$((\mathcal{J} f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]}$$

$$((\mathcal{J} f) x) : \mathbb{R}^{m \times n}$$

$$((\mathcal{J} f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

# A property

$x : \mathbb{R}^n$

$\bar{x} : \mathbb{R}^n$

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]} \quad ((\mathcal{J}f) x) : \mathbb{R}^{m \times n} \quad ((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

(primal ((j\* f) (bundle x  $\bar{x}$ ))) = (f x)

# A property

$x : \mathbb{R}^n$

$\bar{x} : \mathbb{R}^n$

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]} \quad ((\mathcal{J}f) x) : \mathbb{R}^{m \times n} \quad ((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

(primal ((j\* f) (bundle x  $\bar{x}$ ))) = (f x)

(tangent ((j\* f) (bundle x  $\bar{x}$ ))) = (( $\mathcal{J}f$ ) x)  $\times$   $\bar{x}$

# A property

$x : \mathbb{R}^n$

$\bar{x} : \mathbb{R}^n$

$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]} \quad ((\mathcal{J}f) x) : \mathbb{R}^{m \times n} \quad ((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

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(tangent ((j\* f) (bundle x  $\bar{x}$ ))) = ((( $\mathcal{J}f$ ) x)  $\bar{x}$ )

# A property

$x : \mathbb{R}^n$        $\bar{x} : \mathbb{R}^n$        $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]}$      $((\mathcal{J}f) x) : \mathbb{R}^{m \times n}$      $((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$

(primal ((j\* f) (bundle x  $\bar{x}$ ))) = (f x)

(tangent ((j\* f) (bundle x  $\bar{x}$ ))) = (( $\mathcal{J}f$ ) x)  $\times$   $\bar{x}$

(tangent ((j\* f) (bundle x  $\bar{x}$ ))) = ((( $\mathcal{J}f$ ) x)  $\bar{x}$ )

((j\* f) x) = (bundle (f (primal x)) ((( $\mathcal{J}f$ ) (primal x)) (tangent x)))

# A property

$x : \mathbb{R}^n$        $\bar{x} : \mathbb{R}^n$        $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]}$      $((\mathcal{J}f) x) : \mathbb{R}^{m \times n}$      $((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$

(primal ((j\* f) (bundle x  $\bar{x}$ ))) = (f x)

(tangent ((j\* f) (bundle x  $\bar{x}$ ))) = (( $\mathcal{J}f$ ) x)  $\times$   $\bar{x}$

(tangent ((j\* f) (bundle x  $\bar{x}$ ))) = ((( $\mathcal{J}f$ ) x)  $\bar{x}$ )

((j\* f) x) = (bundle (f (primal x)) ((( $\mathcal{J}f$ ) (primal x)) (tangent x)))

rearrangement function:  $(\forall i)(\exists j)(f x)[i] = x[j]$

# A property

$x : \mathbb{R}^n$        $\bar{x} : \mathbb{R}^n$        $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$

$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]}$      $((\mathcal{J}f) x) : \mathbb{R}^{m \times n}$      $((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$

(primal ((j\* f) (bundle x  $\bar{x}$ ))) = (f x)

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rearrangement function:  $(\forall i)(\exists j)(f x)[i] = x[j]$

$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$

# A property

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$$((\mathcal{J}f) x)$$

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Problem avoided if we take  $\overline{\#t} = \#t$

# What is $(\text{j}* \quad \text{j}* )$ ?

# What is ( $\text{j}* \text{j}* \text{j}$ )?

when  $f$  is a rearrangement function

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# What is ( $j^*$ $j^*$ )?

when  $f$  is a rearrangement function

$$((j^* f) x) = (\text{bundle } (f \ (\text{primal } x)) \ (f \ (\text{tangent } x)))$$

`bundle`, `primal`, `tangent`, and  $j^*$  are rearrangement functions

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# A (Not So) Brief Tutorial on AD

$$z = g(f(x))$$

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$$\begin{aligned} z &= g(f(x)) \\ &= (f \circ g)(x) \end{aligned}$$

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$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx}$$

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$$\mathcal{D}(f \circ g)x = (\mathcal{D}g y) \times (\mathcal{D}f x)$$

# A (Not So) Brief Tutorial on AD

$$f = f_1 \circ \cdots \circ f_n$$

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$$f = f_1 \circ \cdots \circ f_n$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

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$$f = f_1 \circ \cdots \circ f_n$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\mathcal{J} f \mathbf{x}_0 = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0)$$

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$$(\mathcal{J} f \mathbf{x}_0)^\top = (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top$$

# A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{X}}'_n = \mathcal{J} f \mathbf{x}_0$$

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$$\begin{aligned}\overline{\mathbf{X}}'_n &= \mathcal{J} f \ \mathbf{x}_0 \\ &= (\mathcal{J} f_n \ \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_2 \ \mathbf{x}_1) \times (\mathcal{J} f_1 \ \mathbf{x}_0)\end{aligned}$$

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$$\overline{\mathbf{X}}'_1 = (\mathcal{J} f_1 \mathbf{x}_0)$$

$$\overline{\mathbf{X}}'_2 = (\mathcal{J} f_2 \mathbf{x}_1) \times \overline{\mathbf{X}}'_1$$

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$$\overrightarrow{\mathbf{X}}'_n = \mathcal{J} f \mathbf{x}_0$$

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⋮

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$$\overline{\mathbf{X}_{n-1}} = (\mathcal{J} f_n \mathbf{x}_{n-1})^\top$$

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$$\overline{\mathbf{X}_0} = (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{X}_1}$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{rcl} \overrightarrow{\mathbf{X}_1} & = & (\mathcal{J} f_1 \mathbf{x}_0) \\ \overrightarrow{\mathbf{X}_2} & = & (\mathcal{J} f_2 \mathbf{x}_1) \times \overrightarrow{\mathbf{X}_1} \\ & \vdots & \\ \overrightarrow{\mathbf{X}_n} & = & (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overrightarrow{\mathbf{X}_{n-1}} \end{array} \qquad \begin{array}{rcl} \overrightarrow{\mathbf{X}_{n-1}} & = & (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overrightarrow{\mathbf{X}_{n-2}} & = & (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overrightarrow{\mathbf{X}_{n-1}} \\ & \vdots & \\ \overrightarrow{\mathbf{X}_0} & = & (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overrightarrow{\mathbf{X}_1} \end{array}$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{rcl} \overrightarrow{\mathbf{X}_1} & = & (\mathcal{J} f_1 \mathbf{x}_0) \\ \overrightarrow{\mathbf{X}_2} & = & (\mathcal{J} f_2 \mathbf{x}_1) \times \overrightarrow{\mathbf{X}_1} \\ & \vdots & \\ \overrightarrow{\mathbf{X}_n} & = & (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overrightarrow{\mathbf{X}_{n-1}} \end{array} \qquad \begin{array}{rcl} \overrightarrow{\mathbf{X}_{n-1}} & = & (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overrightarrow{\mathbf{X}_{n-2}} & = & (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overrightarrow{\mathbf{X}_{n-1}} \\ & \vdots & \\ \overrightarrow{\mathbf{X}_0} & = & (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overrightarrow{\mathbf{X}_1} \end{array}$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{rcl} \overline{\mathbf{X}_1} & = & (\mathcal{J} f_1 \mathbf{x}_0) \\ \overline{\mathbf{X}_2} & = & (\mathcal{J} f_2 \mathbf{x}_1) \times \overline{\mathbf{X}_1} \\ & \vdots & \\ \overline{\mathbf{X}_n} & = & (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overline{\mathbf{X}_{n-1}} \end{array} \qquad \begin{array}{rcl} \overline{\mathbf{X}_{n-1}} & = & (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \\ \overline{\mathbf{X}_{n-2}} & = & (\mathcal{J} f_{n-1} \mathbf{x}_{n-2})^\top \times \overline{\mathbf{X}_{n-1}} \\ & \vdots & \\ \overline{\mathbf{X}_0} & = & (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overline{\mathbf{X}_1} \end{array}$$

# A (Not So) Brief Tutorial on AD

$$\overrightarrow{\mathbf{x}_n} = (\mathcal{J} f \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overrightarrow{\mathbf{x}_n} &= (\mathcal{J} f \ \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0} \\ &= (\mathcal{J} f_n \ \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \ \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\overrightarrow{\mathbf{x}_n} = (\mathcal{J} f \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0}$$

$$= (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0}$$

$$\overrightarrow{\mathbf{x}_1} = (\mathcal{J} f_1 \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0}$$

⋮

$$\overrightarrow{\mathbf{x}_n} = (\mathcal{J} f_n \mathbf{x}_{n-1}) \times \overrightarrow{\mathbf{x}_{n-1}}$$

# A (Not So) Brief Tutorial on AD

$$\overleftarrow{\mathbf{x}_0} = (\mathcal{J}f \ \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}_n}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overleftarrow{\mathbf{x}_0} &= (\mathcal{J}f \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}_n} \\ &= (\mathcal{J}f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J}f_n \mathbf{x}_{n-1})^\top \times \overleftarrow{\mathbf{x}_n}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\overleftarrow{\mathbf{x}_0} = (\mathcal{J} f \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}_n}$$
$$= (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \times \overleftarrow{\mathbf{x}_n}$$

$$\overleftarrow{\mathbf{x}_{n-1}} = (\mathcal{J} f_n \mathbf{x}_{n-1})^\top \times \overleftarrow{\mathbf{x}_n}$$

⋮

$$\overleftarrow{\mathbf{x}_0} = (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}_1}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{y} = \mathbf{A} \times \mathbf{x}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\overrightarrow{\mathbf{x}_n} = (\mathcal{J} f \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\begin{aligned}\overrightarrow{\mathbf{x}_n} &= (\mathcal{J} f \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0} \\ &= \overrightarrow{f} \mathbf{x}_0 \overrightarrow{\mathbf{x}_0}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\begin{aligned}\overrightarrow{\mathbf{x}_n} &= (\mathcal{J} f \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0} \\ &= \overrightarrow{f} \mathbf{x}_0 \overrightarrow{\mathbf{x}_0}\end{aligned}$$

$$\overleftarrow{\mathbf{x}_0} = (\mathcal{J} f \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}_n}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{A} \times \mathbf{x} \\ &= f(\mathbf{x})\end{aligned}$$

$$\begin{aligned}\overrightarrow{\mathbf{x}_n} &= (\mathcal{J} f \mathbf{x}_0) \times \overrightarrow{\mathbf{x}_0} \\ &= \overrightarrow{f} \mathbf{x}_0 \overrightarrow{\mathbf{x}_0}\end{aligned}$$

$$\begin{aligned}\overleftarrow{\mathbf{x}_0} &= (\mathcal{J} f \mathbf{x}_0)^\top \times \overleftarrow{\mathbf{x}_n} \\ &= \overleftarrow{f} \mathbf{x}_0 \overleftarrow{\mathbf{x}_n}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{X}}_n[;j] = \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[;j] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[;j]\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[;j] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[;j]\end{aligned}$$

$$\overline{\mathbf{X}}_0[;i] = \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_i$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[;j] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[;j]\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{X}}_0[;i] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_i \\ &= (\mathcal{J} f \mathbf{x}_0)^\top[;i]\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{X}}_n[;j] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_j \\ &= (\mathcal{J} f \mathbf{x}_0)[;j]\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{X}}_0[;i] &= \overline{f} \mathbf{x}_0 \overline{\mathbf{e}}_i \\ &= (\mathcal{J} f \mathbf{x}_0)^\top[;i] \\ &= (\mathcal{J} f \mathbf{x}_0)[i;]\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{y} = \mathbf{B} \times (\mathbf{A} \times \mathbf{x})$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x}))\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x})) \\ &= (f \circ g)(\mathbf{x})\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x})) \\ &= (f \circ g)(\mathbf{x})\end{aligned}$$

$$(\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) = (\overline{f'_1} \mathbf{x}_0) \circ \cdots \circ (\overline{f'_n} \mathbf{x}_{n-1})$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{y} &= \mathbf{B} \times (\mathbf{A} \times \mathbf{x}) \\ &= (\mathbf{B} \times \mathbf{A}) \times \mathbf{x} \\ &= g(f(\mathbf{x})) \\ &= (f \circ g)(\mathbf{x})\end{aligned}$$

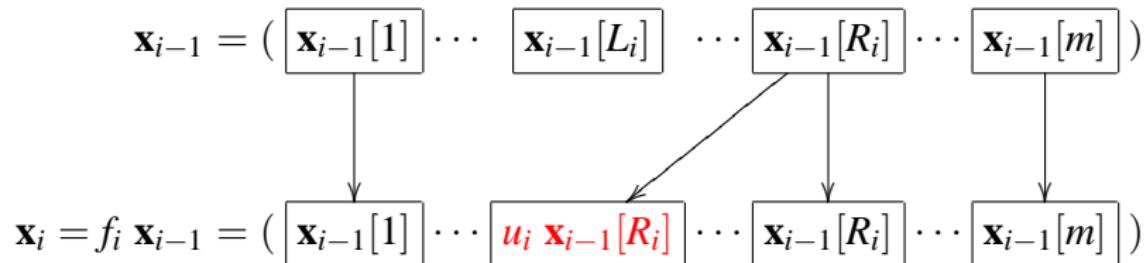
$$\begin{aligned}(\mathcal{J} f_n \mathbf{x}_{n-1}) \times \cdots \times (\mathcal{J} f_1 \mathbf{x}_0) &= (\overline{f'_1} \mathbf{x}_0) \circ \cdots \circ (\overline{f'_n} \mathbf{x}_{n-1}) \\ (\mathcal{J} f_1 \mathbf{x}_0)^\top \times \cdots \times (\mathcal{J} f_n \mathbf{x}_{n-1})^\top &= (\overline{f_n} \mathbf{x}_{n-1}) \circ \cdots \circ (\overline{f_1} \mathbf{x}_0)\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]} )$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{u_i \mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]} )$$

$$\mathbf{x}[L_i] := u_i \mathbf{x}[R_i]$$

# A (Not So) Brief Tutorial on AD



$$\mathbf{x}[L_i] := u_i \mathbf{x}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{u_i \mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

The diagram illustrates the construction of  $\mathbf{x}_i$  from  $\mathbf{x}_{i-1}$ . It shows two rows of boxes representing vectors. The top row contains boxes for  $\mathbf{x}_{i-1}[1], \dots, \mathbf{x}_{i-1}[L_i], \dots, \mathbf{x}_{i-1}[R_i], \dots, \mathbf{x}_{i-1}[m]$ . The bottom row contains boxes for  $\mathbf{x}_{i-1}[1], \dots, u_i \mathbf{x}_{i-1}[R_i], \dots, \mathbf{x}_{i-1}[R_i], \dots, \mathbf{x}_{i-1}[m]$ . Arrows point from the  $R_i$  box in the top row to the  $R_i$  box in the bottom row, and from the  $L_i$  box in the top row to the  $u_i \mathbf{x}_{i-1}[R_i]$  box in the bottom row.

$$\mathbf{x}[L_i] := u_i \mathbf{x}[R_i]$$

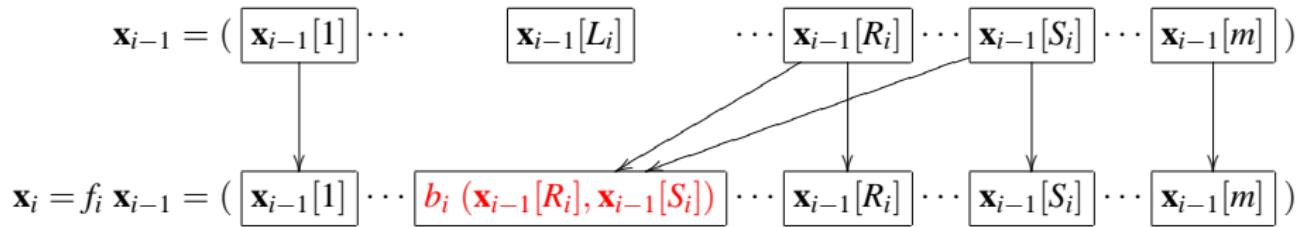
# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

```
graph TD; subgraph x_i_minus_1 ["x_{i-1}"]; 1["x_{i-1}[1]"] --- 2["x_{i-1}[L_i]"]; 2 --- 3["x_{i-1}[R_i]"]; 3 --- 4["x_{i-1}[S_i]"]; 4 --- m["x_{i-1}[m]"]; end; subgraph x_i ["x_i = f_i x_{i-1}"]; 1["x_{i-1}[1]"] --- 2["b_i(x_{i-1}[R_i], x_{i-1}[S_i])"]; 2 --- 3["x_{i-1}[R_i]"]; 3 --- 4["x_{i-1}[S_i]"]; 4 --- m["x_{i-1}[m]"]; end; 1 --> 1; 3 --> 3; 4 --> 4;
```

$$\mathbf{x}[L_i] := b(\mathbf{x}[R_i], \mathbf{x}[S_i])$$

# A (Not So) Brief Tutorial on AD



$$\mathbf{x}[L_i] := b (\mathbf{x}[R_i], \mathbf{x}[S_i])$$

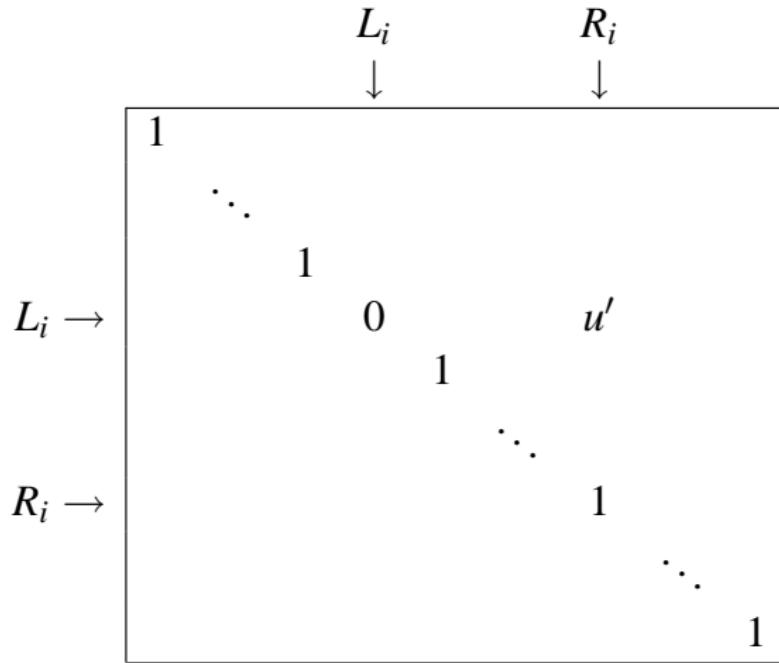
# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{\mathbf{x}_{i-1}[L_i]} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$
$$\mathbf{x}_i = f_i \mathbf{x}_{i-1} = (\boxed{\mathbf{x}_{i-1}[1]} \cdots \boxed{b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])} \cdots \boxed{\mathbf{x}_{i-1}[R_i]} \cdots \boxed{\mathbf{x}_{i-1}[S_i]} \cdots \boxed{\mathbf{x}_{i-1}[m]})$$

The diagram illustrates the construction of  $\mathbf{x}_i$  from  $\mathbf{x}_{i-1}$ . It shows a sequence of boxes representing elements of the vectors. A vertical arrow connects  $\mathbf{x}_{i-1}[1]$  to  $\mathbf{x}_i[1]$ . A diagonal arrow connects  $\mathbf{x}_{i-1}[R_i]$  to  $\mathbf{x}_i[R_i]$ . A vertical arrow connects  $\mathbf{x}_{i-1}[S_i]$  to  $\mathbf{x}_i[S_i]$ . The term  $b_i(\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$  is highlighted in red, indicating its role in the update rule.

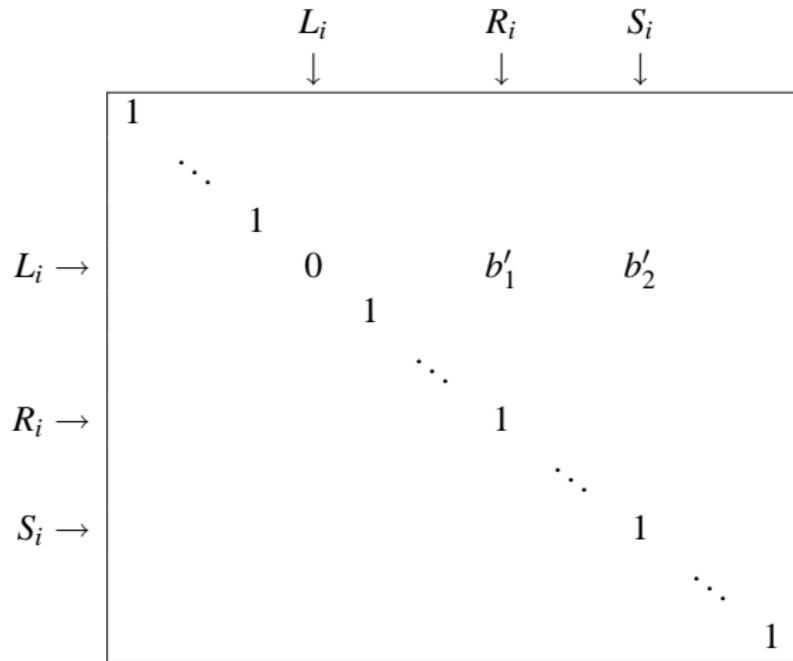
$$\mathbf{x}[L_i] := b (\mathbf{x}[R_i], \mathbf{x}[S_i])$$

# A (Not So) Brief Tutorial on AD



$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD



$$b'_1 = \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$$
$$b'_2 = \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$$

# A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}'_i} = \overline{f'_i} \ \mathbf{x}_{i-1} \ \overline{\mathbf{x}_{i-1}'}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}'_i} &= \overline{f'_i} \ \mathbf{x}_{i-1} \ \overline{\mathbf{x}'_{i-1}} \\ &= (\mathcal{J} f_i \ \mathbf{x}_{i-1}) \times \overline{\mathbf{x}'_{i-1}}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}'_i &= \overline{f_i}' \mathbf{x}_{i-1} \overline{\mathbf{x}_{i-1}'} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}_{i-1}'}\end{aligned}$$

$$\begin{pmatrix} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ u' \times \overline{\mathbf{x}_{i-1}'}[R_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{pmatrix} = \begin{pmatrix} 1 & & & & & & \\ & \ddots & & & & & \\ & & 1 & & & & \\ & & & 0 & & & u' \\ & & & & 1 & & \\ & & & & & \ddots & \\ & & & & & & 1 \\ & & & & & & & \ddots & \\ & & & & & & & & 1 \end{pmatrix} \begin{pmatrix} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ \overline{\mathbf{x}_{i-1}'}[L_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{pmatrix}$$

$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}'_i &= \overline{f_i}' \mathbf{x}_{i-1} \overline{\mathbf{x}_{i-1}'} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}_{i-1}'}\end{aligned}$$

$$\left( \begin{array}{c} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ u' \times \overline{\mathbf{x}_{i-1}'}[R_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \\ & \ddots & & & & & & & \\ & & 1 & & & & & & \\ & & & 0 & & & & u' & \\ & & & & 1 & & & & \\ & & & & & \ddots & & & \\ & & & & & & 1 & & \\ & & & & & & & \ddots & \\ & & & & & & & & 1 \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ \overline{\mathbf{x}_{i-1}'}[L_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{array} \right)$$

$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}'_i &= \overline{f_i}' \mathbf{x}_{i-1} \overline{\mathbf{x}_{i-1}'} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}_{i-1}'}\end{aligned}$$

$$\left( \begin{array}{c} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ u' \times \overline{\mathbf{x}_{i-1}'}[R_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \\ & \ddots & & & & & & & \\ & & 1 & & & & & & \\ & & & 0 & & & & u' & \\ & & & & 1 & & & & \\ & & & & & \ddots & & & \\ & & & & & & 1 & & \\ & & & & & & & \ddots & \\ & & & & & & & & 1 \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ \overline{\mathbf{x}_{i-1}'}[L_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{array} \right)$$

$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}}'_i = \overline{f}'_i \mathbf{x}_{i-1} \overline{\mathbf{x}}'_{i-1}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}'_i &= \overline{f'_i} \mathbf{x}_{i-1} \overline{\mathbf{x}'_{i-1}} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}'_{i-1}}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}}'_i &= \overline{f'_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_{i-1}'} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}_{i-1}'}\end{aligned}$$

$$\left( \begin{array}{c} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ b'_1 \times \overline{\mathbf{x}_{i-1}'}[R_i] + b'_2 \times \overline{\mathbf{x}_{i-1}'}[S_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[S_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \\ & \ddots & & & & & & & \\ & & 1 & & & & & & \\ & & & 0 & & & b'_1 & & b'_2 \\ & & & & 1 & & & & \\ & & & & & \ddots & & & \\ & & & & & & 1 & & \\ & & & & & & & \ddots & \\ & & & & & & & & 1 \\ & & & & & & & & & \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_{i-1}'}[1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[L_i - 1] \\ \overline{\mathbf{x}_{i-1}'}[L_i] \\ \overline{\mathbf{x}_{i-1}'}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[R_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[S_i] \\ \vdots \\ \overline{\mathbf{x}_{i-1}'}[m] \end{array} \right)$$

$$\begin{aligned}b'_1 &= \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i]) \\ b'_2 &= \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\overline{\mathbf{x}}'_i = \overline{f_i}' \mathbf{x}_{i-1} \overline{\mathbf{x}}_{i-1}' \\ = (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}}_{i-1}$$

$$\begin{pmatrix} \overline{\mathbf{x}}_{i-1}'[1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[L_i - 1] \\ \color{red}{b'_1 \times \overline{\mathbf{x}}_{i-1}'[R_i] + b'_2 \times \overline{\mathbf{x}}_{i-1}'[S_i]} \\ \overline{\mathbf{x}}_{i-1}'[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[R_i] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[S_i] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[m] \end{pmatrix} = \begin{pmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & 0 & & b'_1 \\ & & & & 1 & b'_2 \\ & & & & & \ddots \\ & & & & & & 1 \\ & & & & & & & \ddots \\ & & & & & & & & 1 \end{pmatrix} \begin{pmatrix} \overline{\mathbf{x}}_{i-1}'[1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[L_i - 1] \\ \overline{\mathbf{x}}_{i-1}'[L_i] \\ \overline{\mathbf{x}}_{i-1}'[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[R_i] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[S_i] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}'[m] \end{pmatrix}$$

$$b'_1 = \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i]) \\ b'_2 = \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$$

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$$\overline{\mathbf{x}}'_i = \overline{f_i}' \mathbf{x}_{i-1} \overline{\mathbf{x}}_{i-1}' \\ = (\mathcal{J} f_i \mathbf{x}_{i-1}) \times \overline{\mathbf{x}}_{i-1}$$

$$\begin{pmatrix} \overline{\mathbf{x}}_{i-1}[1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}[L_i - 1] \\ \color{red}{b'_1 \times \overline{\mathbf{x}}_{i-1}[R_i] + b'_2 \times \overline{\mathbf{x}}_{i-1}[S_i]} \\ \overline{\mathbf{x}}_{i-1}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}[R_i] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}[S_i] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}[m] \end{pmatrix} = \begin{pmatrix} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ & & & 0 & & b'_1 \\ & & & & 1 & b'_2 \\ & & & & & \ddots \\ & & & & & & 1 \\ & & & & & & & \ddots \\ & & & & & & & & 1 \end{pmatrix} \begin{pmatrix} \overline{\mathbf{x}}_{i-1}[1] \\ \vdots \\ \overline{\mathbf{x}}_{i-1}[L_i - 1] \\ \color{green}{\overline{\mathbf{x}}_{i-1}[R_i]} \\ \overline{\mathbf{x}}_{i-1}[L_i] \\ \color{green}{\overline{\mathbf{x}}_{i-1}[S_i]} \\ \vdots \\ \overline{\mathbf{x}}_{i-1}[m] \end{pmatrix}$$

$$b'_1 = \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i]) \\ b'_2 = \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])$$

# A (Not So) Brief Tutorial on AD

$$\overbrace{\mathbf{x}_{i-1}} = \overbrace{f_i} \mathbf{x}_{i-1} \overbrace{\mathbf{x}_i}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

$$\begin{pmatrix} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ 0 \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ u' \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{pmatrix} = \begin{pmatrix} 1 & & & & & & & \\ & \ddots & & & & & & \\ & & 1 & & & & & \\ & & & 0 & & & & \\ & & & & 1 & & & \\ & & & & & \ddots & & \\ & & & & & & 1 & \\ & & & & & & & \ddots \\ & & & & & & & & 1 \end{pmatrix} \begin{pmatrix} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \overline{\mathbf{x}_i}[L_i] \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{pmatrix}$$

$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

$$\begin{pmatrix} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \color{red}{0} \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ u' \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{pmatrix} = \begin{pmatrix} 1 & & & & & & & \overline{\mathbf{x}_i}[1] \\ & \ddots & & & & & & \vdots \\ & & 1 & & & & & \overline{\mathbf{x}_i}[L_i - 1] \\ & & & 0 & & & & \overline{\mathbf{x}_i}[L_i] \\ & & & & 1 & & & \overline{\mathbf{x}_i}[L_i + 1] \\ & & & & & \ddots & & \vdots \\ & & & & & & 1 & \overline{\mathbf{x}_i}[R_i] \\ & & & & & & & \vdots \\ & & & & & & & \overline{\mathbf{x}_i}[m] \end{pmatrix} \begin{pmatrix} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \overline{\mathbf{x}_i}[L_i] \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{pmatrix}$$

$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

$$\left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \color{red}{0} \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ u' \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \overline{\mathbf{x}_i}[1] \\ & \ddots & & & & & & & \vdots \\ & & 1 & & & & & & \overline{\mathbf{x}_i}[L_i - 1] \\ & & & 0 & & & & & \color{green}{\overline{\mathbf{x}_i}[L_i]} \\ & & & & 1 & & & & \overline{\mathbf{x}_i}[L_i + 1] \\ & & & & & \ddots & & & \vdots \\ & & & & & & 1 & & \color{green}{\overline{\mathbf{x}_i}[R_i]} \\ & & & & & & & \ddots & \\ & & & & & & & & 1 \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \color{green}{\overline{\mathbf{x}_i}[L_i]} \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \color{green}{\overline{\mathbf{x}_i}[R_i]} \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right)$$

$$u' = \mathcal{D} u_i \mathbf{x}_{i-1}[R_i]$$

# A (Not So) Brief Tutorial on AD

$$\overbrace{\mathbf{x}_{i-1}} = \overbrace{f_i} \mathbf{x}_{i-1} \overbrace{\mathbf{x}_i}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

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$$\left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ 0 \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ b'_1 \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ b'_2 \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[S_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \\ & \ddots & & & & & & & \\ & & 1 & & & & & & \\ & & & 0 & & & & & \\ & & & & 1 & & & & \\ & & & & & \ddots & & & \\ & & & & b'_1 & & 1 & & \\ & & & & & b'_2 & & & \\ & & & & & & \ddots & & \\ & & & & & & & 1 & \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \overline{\mathbf{x}_i}[L_i] \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[S_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right)$$

$$\begin{aligned}b'_1 &= \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i]) \\ b'_2 &= \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

$$\left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \color{red}{\mathbf{0}} \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \color{red}{b'_1 \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[R_i]} \\ \vdots \\ \color{red}{b'_2 \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[S_i]} \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \\ & \ddots & & & & & & & \\ & & 1 & & & & & & \\ & & & 0 & & & & & \\ & & & & 1 & & & & \\ & & & & & \ddots & & & \\ & & & b'_1 & & & 1 & & \\ & & & & b'_2 & & & \ddots & \\ & & & & & & & 1 & \\ & & & & & & & & \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \overline{\mathbf{x}_i}[L_i] \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \overline{\mathbf{x}_i}[R_i] \\ \vdots \\ \overline{\mathbf{x}_i}[S_i] \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right)$$

$$\begin{aligned}b'_1 &= \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i]) \\ b'_2 &= \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\overline{\mathbf{x}_{i-1}} &= \overline{f_i} \mathbf{x}_{i-1} \overline{\mathbf{x}_i} \\ &= (\mathcal{J} f_i \mathbf{x}_{i-1})^\top \times \overline{\mathbf{x}_i}\end{aligned}$$

$$\left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \color{red}{\mathbf{0}} \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \color{red}{b'_1 \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[R_i]} \\ \vdots \\ \color{red}{b'_2 \times \overline{\mathbf{x}_i}[L_i] + \overline{\mathbf{x}_i}[S_i]} \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right) = \left( \begin{array}{ccccccccc} 1 & & & & & & & & \\ & \ddots & & & & & & & \\ & & 1 & & & & & & \\ & & & 0 & & & & & \\ & & & & 1 & & & & \\ & & & & & \ddots & & & \\ & & & b'_1 & & & 1 & & \\ & & & & b'_2 & & & \ddots & \\ & & & & & & & 1 & \\ & & & & & & & & \end{array} \right) \left( \begin{array}{c} \overline{\mathbf{x}_i}[1] \\ \vdots \\ \overline{\mathbf{x}_i}[L_i - 1] \\ \color{green}{\overline{\mathbf{x}_i}[L_i]} \\ \overline{\mathbf{x}_i}[L_i + 1] \\ \vdots \\ \color{green}{\overline{\mathbf{x}_i}[R_i]} \\ \vdots \\ \color{green}{\overline{\mathbf{x}_i}[S_i]} \\ \vdots \\ \overline{\mathbf{x}_i}[m] \end{array} \right)$$

$$\begin{aligned}b'_1 &= \mathcal{D}_1 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i]) \\ b'_2 &= \mathcal{D}_2 b_i (\mathbf{x}_{i-1}[R_i], \mathbf{x}_{i-1}[S_i])\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

 $\vdots$ 

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}}'_1 = \overline{f'_1} \mathbf{x}_0 \overline{\mathbf{x}}'_0$$

 $\vdots$ 

$$\overline{\mathbf{x}}'_n = \overline{f'_n} \mathbf{x}_{n-1} \overline{\mathbf{x}}'_{n-1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\overline{\mathbf{x}}'_1 = \overline{f'_1} \mathbf{x}_0 \overline{\mathbf{x}}'_0$$

 $\vdots$ 

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}}'_n = \overline{f'_n} \mathbf{x}_{n-1} \overline{\mathbf{x}}'_{n-1}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overrightarrow{\mathbf{x}_1} = \overrightarrow{f_1} \mathbf{x}_0 \overrightarrow{\mathbf{x}_0}$$

⋮

$$\overrightarrow{\mathbf{x}_n} = \overrightarrow{f_n} \mathbf{x}_{n-1} \overrightarrow{\mathbf{x}_{n-1}}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\overrightarrow{\mathbf{x}_1} = \overrightarrow{f_1} \mathbf{x}_0 \overrightarrow{\mathbf{x}_0}$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overrightarrow{\mathbf{x}_n} = \overrightarrow{f_n} \mathbf{x}_{n-1} \overrightarrow{\mathbf{x}_{n-1}}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}}'_1 = \overline{f'_1} \mathbf{x}_0 \overline{\mathbf{x}}'_0$$

⋮

$$\overline{\mathbf{x}}'_n = \overline{f'_n} \mathbf{x}_{n-1} \overline{\mathbf{x}}'_{n-1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\overline{\mathbf{x}}'_1 = \overline{f'_1} \mathbf{x}_0 \overline{\mathbf{x}}'_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}}'_n = \overline{f'_n} \mathbf{x}_{n-1} \overline{\mathbf{x}}'_{n-1}$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{rcl} \mathbf{x}_1 & = & f_1 \mathbf{x}_0 \\ \overline{\mathbf{x}'_1} & = & \overline{f'_1} \mathbf{x}_0 \overline{\mathbf{x}'_0} \end{array}$$

⋮

$$\begin{array}{rcl} \mathbf{x}_n & = & f_n \mathbf{x}_{n-1} \\ \overline{\mathbf{x}'_n} & = & \overline{f'_n} \mathbf{x}_{n-1} \overline{\mathbf{x}'_{n-1}} \end{array}$$

$$(\mathbf{x}_1, \overline{\mathbf{x}'_1}) = ((f_1 \mathbf{x}_0), (\overline{f'_1} \mathbf{x}_0 \overline{\mathbf{x}'_0}))$$

⋮

$$(\mathbf{x}_n, \overline{\mathbf{x}'_n}) = ((f_n \mathbf{x}_{n-1}), (\overline{f'_n} \mathbf{x}_{n-1} \overline{\mathbf{x}'_{n-1}}))$$

# A (Not So) Brief Tutorial on AD

$$\left. \begin{array}{l} \mathbf{x}_1 = f_1 \mathbf{x}_0 \\ \vdots \\ \mathbf{x}_n = f_n \mathbf{x}_{n-1} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \overrightarrow{\mathbf{x}}_1 = \overrightarrow{f_1} \overrightarrow{\mathbf{x}}_0 \\ \vdots \\ \overrightarrow{\mathbf{x}}_n = \overrightarrow{f_n} \overrightarrow{\mathbf{x}}_{n-1} \end{array} \right.$$

$$\begin{aligned}\overrightarrow{\mathbf{x}} &\equiv (\mathbf{x}, \overline{\mathbf{x}}) \\ \overrightarrow{f} \overrightarrow{\mathbf{x}} &\equiv ((f \mathbf{x}), (\overline{f}' \mathbf{x} \overline{\mathbf{x}}))\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{lcl} x_{L_i} := u_i \; x_{R_i} & \rightsquigarrow & \overrightarrow{x_{L_i}} := \overrightarrow{u_i} \; \overrightarrow{x_{R_i}} \\ x_{L_i} := b_i \; (x_{R_i}, x_{S_i}) & \rightsquigarrow & \overrightarrow{x_{L_i}} := \overrightarrow{b_i} \; (\overrightarrow{x_{R_i}}, \overrightarrow{x_{S_i}}) \end{array}$$

$$\overrightarrow{x} \equiv (x, \overrightarrow{x})$$

$$\overrightarrow{u} \; \overrightarrow{x} \equiv ((u \; x), ((\mathcal{D} \; u \; x) \times \overrightarrow{x}))$$

$$\overrightarrow{b} \; (\overrightarrow{x_1}, \overrightarrow{x_2}) \equiv ((b \; (x_1, x_2)), ((\mathcal{D}_1 \; b \; (x_1, x_2)) \times \overrightarrow{x_1}) + ((\mathcal{D}_2 \; b \; (x_1, x_2)) \times \overrightarrow{x_2})))$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

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# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

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$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

# A (Not So) Brief Tutorial on AD

$$\begin{aligned}\mathbf{x}_1 &= f_1 \mathbf{x}_0 \\ &\vdots \\ \mathbf{x}_n &= f_n \mathbf{x}_{n-1}\end{aligned}$$

$$\begin{aligned}\overline{\mathbf{x}_{n-1}} &= \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n} \\ &\vdots \\ \overline{\mathbf{x}_0} &= \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}\end{aligned}$$

$$\begin{aligned}\mathbf{x}_1 &= f_1 \mathbf{x}_0 \\ &\vdots \\ \mathbf{x}_n &= f_n \mathbf{x}_{n-1} \\ \overline{\mathbf{x}_{n-1}} &= \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n} \\ &\vdots \\ \overline{\mathbf{x}_0} &= \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}\end{aligned}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

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$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_{n-1}} = \overline{f_n} \mathbf{x}_{n-1} \overline{\mathbf{x}_n}$$

⋮

$$\overline{\mathbf{x}_0} = \overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}_1}$$

# A (Not So) Brief Tutorial on AD

$$\mathbf{x}_1 = f_1 \mathbf{x}_0$$

$$\overline{\mathbf{x}_1} = \lambda^{\overline{\mathbf{x}}} \overline{\mathbf{x}_0} (\overline{f_1} \mathbf{x}_0 \overline{\mathbf{x}})$$

⋮

$$\mathbf{x}_n = f_n \mathbf{x}_{n-1}$$

$$\overline{\mathbf{x}_n} = \lambda^{\overline{\mathbf{x}}} \overline{\mathbf{x}_{n-1}} (\overline{f_n} \mathbf{x}_0 \overline{\mathbf{x}})$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{lcl} \mathbf{x}_1 & = & f_1 \mathbf{x}_0 \\ \overline{\mathbf{x}_1} & = & \lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}_0} (\overline{f_1} \ \mathbf{x}_0 \ \overline{\mathbf{x}}) \end{array}$$

⋮

$$\begin{array}{lcl} \mathbf{x}_n & = & f_n \mathbf{x}_{n-1} \\ \overline{\mathbf{x}_n} & = & \lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}_{n-1}} (\overline{f_1} \ \mathbf{x}_0 \ \overline{\mathbf{x}}) \end{array}$$



$$(\mathbf{x}_1, \overline{\mathbf{x}_1}) = ((f_1 \mathbf{x}_0), (\lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}_0} (\overline{f_1} \ \mathbf{x}_0 \ \overline{\mathbf{x}})))$$

⋮

$$(\mathbf{x}_n, \overline{\mathbf{x}_n}) = ((f_n \mathbf{x}_{n-1}), (\lambda \overline{\mathbf{x}} \ \overline{\mathbf{x}_{n-1}} (\overline{f_1} \ \mathbf{x}_0 \ \overline{\mathbf{x}})))$$

# A (Not So) Brief Tutorial on AD

$$\left. \begin{array}{l} \mathbf{x}_1 = f_1 \mathbf{x}_0 \\ \vdots \\ \mathbf{x}_n = f_n \mathbf{x}_{n-1} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \overleftarrow{\mathbf{x}_1} = \overleftarrow{f_1} \overleftarrow{\mathbf{x}_0} \\ \vdots \\ \overleftarrow{\mathbf{x}_n} = \overleftarrow{f_n} \overleftarrow{\mathbf{x}_{n-1}} \end{array} \right.$$

$$\overleftarrow{\mathbf{x}} \equiv (\mathbf{x}, \bar{\mathbf{x}})$$

$$\overleftarrow{f} \overleftarrow{\mathbf{x}} \equiv ((f \mathbf{x}), (\lambda \overleftarrow{\mathbf{x}} \bar{\mathbf{x}} (\overleftarrow{f} \mathbf{x} \overleftarrow{\mathbf{x}})))$$

# A (Not So) Brief Tutorial on AD

$$\overleftarrow{f} \text{ } \mathbf{x} \equiv \mathbf{begin} \bar{x} := \lambda \overleftarrow{\mathbf{x}} \quad \bar{x} (\overleftarrow{f} \text{ } \mathbf{x} \text{ } \overleftarrow{\mathbf{x}}); \\ (f \text{ } \mathbf{x}) \mathbf{end}$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{lcl} x_{L_i} := u_i \; x_{R_i} & \rightsquigarrow & \left\{ \begin{array}{l} \bar{x} := \lambda[] \; \mathbf{begin} \; \overline{x_{R_i}} +:= (\mathcal{D} \; u_i \; \overleftarrow{x_{R_i}}) \times \overline{x_{L_i}}; \\ \quad \overline{x_{L_i}} := 0; \\ \quad \bar{x} [] \; \mathbf{end} \\ \\ \overleftarrow{x_{L_i}} := u_i \; \overleftarrow{x_{R_i}} \end{array} \right. \\ \\ x_{L_i} := b_i \; (x_{R_i}, x_{S_i}) & \rightsquigarrow & \left\{ \begin{array}{l} \bar{x} := \lambda[] \; \mathbf{begin} \; \overline{x_{R_i}} +:= (\mathcal{D}_1 \; b_i \; (\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})) \times \overline{x_{L_i}}; \\ \quad \overline{x_{S_i}} +:= (\mathcal{D}_2 \; b_i \; (\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})) \times \overline{x_{L_i}}; \\ \quad \overline{x_{L_i}} := 0; \\ \quad \bar{x} [] \; \mathbf{end} \\ \\ \overleftarrow{x_{L_i}} := b_i \; (\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}}) \end{array} \right. \end{array}$$

$$\overleftarrow{x} \equiv x$$

# A (Not So) Brief Tutorial on AD

$$\begin{array}{lcl} x_{L_i} := u_i \; x_{R_i} & \rightsquigarrow & \left\{ \begin{array}{l} \overleftarrow{x_{L_i}} := u_i \; \overleftarrow{x_{R_i}} \\ \vdots \\ \overleftarrow{x_{R_i}} +:= (\mathcal{D} \; u_i \; \overleftarrow{x_{R_i}}) \times \overleftarrow{x_{L_i}}; \\ \overleftarrow{x_{L_i}} := 0 \\ \overleftarrow{x_{L_i}} := b_i \; (\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}}) \\ \vdots \\ \overleftarrow{x_{R_i}} +:= (\mathcal{D}_1 \; b_i \; (\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})) \times \overleftarrow{x_{L_i}}; \\ \overleftarrow{x_{S_i}} +:= (\mathcal{D}_2 \; b_i \; (\overleftarrow{x_{R_i}}, \overleftarrow{x_{S_i}})) \times \overleftarrow{x_{L_i}}; \\ \overleftarrow{x_{L_i}} := 0 \end{array} \right. \\ \\ x_{L_i} := b_i \; (x_{R_i}, x_{S_i}) & \rightsquigarrow & \left\{ \begin{array}{l} \overleftarrow{x} \equiv x \end{array} \right. \end{array}$$

# The Functional Reverse-Mode Transformation

$$x_{L_1} := u_1 \ x_{S_1}$$

⋮

$$x_{L_n} := u_n \ x_{S_n}$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} +:= (\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} +:= (\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} +:= (\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} +:= (\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} +:= (\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} +:= (\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} x_{L_1} := u_1 x_{S_1} \\ \vdots \\ x_{L_n} := u_n x_{S_n} \\ \overline{x_1} := 0 \\ \vdots \\ \overline{x_m} := 0 \\ \overline{x_{S_n}} +:= (\mathcal{D} u_n x_{S_n}) \times \overline{x_{L_n}} \\ \overline{x_{L_n}} := 0 \\ \vdots \\ \overline{x_{S_1}} +:= (\mathcal{D} u_1 x_{S_1}) \times \overline{x_{L_1}} \\ \overline{x_{L_1}} := 0 \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{rcl} x_1 & = & u_1 \ x_{S_1} \\ \vdots & & \vdots \\ x_n & = & u_n \ x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{rcl} x_1 & = & u_1 \ x_{S_1} \\ \vdots & & \vdots \\ \overline{x_0} & := & 0 \\ \vdots & & \vdots \\ \overline{x_{n-1}} & := & 0 \\ \overline{x_{S_n}} & +:= & (\mathcal{D} \ u_n \ x_{S_n}) \times \overline{x_n} \\ \vdots & & \vdots \\ \overline{x_{S_1}} & +:= & (\mathcal{D} \ u_1 \ x_{S_1}) \times \overline{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} x_1 & = & u_1 x_{S_1} \\ \vdots & & \vdots \\ \overline{x_0} & := & 0 \\ \vdots & & \vdots \\ \overline{x_{n-1}} & := & 0 \\ \overline{x_{S_n}} & +:= & (\mathcal{D} u_n x_{S_n}) \times \overline{x_n} \\ \vdots & & \vdots \\ \overline{x_{S_1}} & +:= & (\mathcal{D} u_1 x_{S_1}) \times \overline{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\overline{u_i} \triangleq \lambda \overleftarrow{x} (\mathcal{D} u_i x_{S_i}) \times \overleftarrow{x}$$

$$\left. \begin{array}{lcl} x_1 & = & u_1 x_{S_1} \\ \vdots & & \vdots \\ x_n & = & u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} x_1 & = & u_1 x_{S_1} \\ \vdots & & \vdots \\ x_n & = & u_n x_{S_n} \\ \overline{x_0} & := & 0 \\ \vdots & & \vdots \\ \overline{x_{n-1}} & := & 0 \\ \overline{x_{S_n}} & +:= & \overline{u_n} \overleftarrow{x_n} \\ \vdots & & \vdots \\ \overline{x_{S_1}} & +:= & \overline{u_1} \overleftarrow{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\overleftarrow{u} \ x \triangleq ((u \ x), (\lambda \overline{x} (\mathcal{D} \ u \ x) \times \overline{x}))$$

$$\left. \begin{array}{l} x_1 = u_1 x_{S_1} \\ \vdots \\ x_n = u_n x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (x_1, \overline{x_1}) & = & \overleftarrow{u_1} x_{S_1} \\ \vdots & & \vdots \\ (x_n, \overline{x_n}) & = & \overleftarrow{u_n} x_{S_n} \\ \overline{x_0} & := & 0 \\ \vdots & & \vdots \\ \overline{x_{n-1}} & := & 0 \\ \overline{x_{S_n}} & +:= & \overline{x_n} \ \overline{x_n} \\ \vdots & & \vdots \\ \overline{x_{S_1}} & +:= & \overline{x_1} \ \overline{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\overleftarrow{u} \ x \stackrel{\Delta}{=} ((u \ x), (\lambda \overline{x}(\mathcal{D} \ u \ x) \times \overline{x}))$$

$$\left. \begin{array}{lcl} x_1 & = & \textcolor{red}{u}_1 \ x_{S_1} \\ \vdots & & \\ x_n & = & \textcolor{red}{u}_n \ x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (x_1, \overline{x_1}) & = & \overleftarrow{u}_1 \ x_{S_1} \\ \vdots & & \\ (x_n, \overline{x_n}) & = & \overleftarrow{u}_n \ x_{S_n} \\ \overline{x_0} & := & 0 \\ \vdots & & \\ \overline{x_{n-1}} & := & 0 \\ \overline{x_{S_n}} & +:= & \overline{x_n} \ \overline{x_n} \\ \vdots & & \\ \overline{x_{S_1}} & +:= & \overline{x_1} \ \overline{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{l} x_1 = \cancel{x_{R_1}} x_{S_1} \\ \vdots \\ x_n = \cancel{x_{R_n}} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (\overleftarrow{x_1}, \overline{x_1}) & = & \cancel{\overleftarrow{x_{R_1}}} \overleftarrow{x_{S_1}} \\ \vdots & & \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) & = & \cancel{\overleftarrow{x_{R_n}}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} & := & 0 \\ \vdots & & \vdots \\ \overleftarrow{x_{n-1}} & := & 0 \\ \overleftarrow{x_{S_n}} & +:= & \overline{x_n} \overleftarrow{x_n} \\ \vdots & & \vdots \\ \overleftarrow{x_{S_1}} & +:= & \overline{x_1} \overleftarrow{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left\{ \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (\overleftarrow{x_1}, \overline{x_1}) & = & \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots & & \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) & = & \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} & := & 0 \\ \vdots & & \vdots \\ \overleftarrow{x_{n-1}} & := & 0 \\ \overleftarrow{x_{S_n}} & +:= & \overline{x_n} \overleftarrow{x_n} \\ \vdots & & \vdots \\ \overleftarrow{x_{S_1}} & +:= & \overline{x_1} \overleftarrow{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (\overleftarrow{x_1}, \overline{x_1}) & = & \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots & & \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) & = & \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} & := & \mathbf{0} \\ \vdots & & \vdots \\ \overleftarrow{x_{n-1}} & := & \mathbf{0} \\ \overleftarrow{x_{S_n}} & +:= & \overline{x_n} \overleftarrow{x_n} \\ \vdots & & \vdots \\ \overleftarrow{x_{S_1}} & +:= & \overline{x_1} \overleftarrow{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (\overleftarrow{x_1}, \overline{x_1}) & = & \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ \vdots & & \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) & = & \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \overleftarrow{x_0} & := & 0 \\ \vdots & & \vdots \\ \overleftarrow{x_{n-1}} & := & 0 \\ \overleftarrow{x_{S_n}} & +:= & \overline{x_n} \overleftarrow{x_n} \\ \vdots & & \vdots \\ \overleftarrow{x_{S_1}} & +:= & \overline{x_1} \overleftarrow{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} x_1 = x_{R_1} x_{S_1} \\ \vdots \\ x_n = x_{R_n} x_{S_n} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{lcl} (\overleftarrow{x_1}, \overline{x_1}) & = & \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}} \\ & \vdots & \\ (\overleftarrow{x_n}, \overline{x_n}) & = & \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ & \overleftarrow{x_0} & := \textcolor{red}{\mathbf{0}(\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x_0})} \\ & \vdots & \\ \overleftarrow{x_{n-1}} & := & \textcolor{red}{\mathbf{0}(\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x_{n-1}})} \\ & \overleftarrow{x_{S_n}} & \oplus:= \overline{x_n} \overleftarrow{x_n} \\ & \vdots & \\ \overleftarrow{x_{S_1}} & \oplus:= & \overline{x_1} \overleftarrow{x_1} \end{array} \right.$$

# The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} \lambda x_0 \text{ let } x_1 \stackrel{\triangle}{=} x_{R_1} x_{S_1}; \\ \vdots \\ x_n \stackrel{\triangle}{=} x_{R_n} x_{S_n} \\ \text{in } x_n \text{ end} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \lambda \overleftarrow{x_0} \text{ let } (\overleftarrow{x_1}, \overline{x_1}) \stackrel{\triangle}{=} \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}}; \\ \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) \stackrel{\triangle}{=} \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \text{in } (\overleftarrow{x_n}, (\lambda \overleftarrow{x_n} \text{ let } \overleftarrow{x_0} \stackrel{\triangle}{=} \mathbf{0} (\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x_0})) \\ \vdots \\ \overleftarrow{x_{n-1}} \stackrel{\triangle}{=} \mathbf{0} (\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x_{n-1}}); \\ \overleftarrow{x_{S_n}} \oplus \stackrel{\triangle}{=} \overline{x_n} \overleftarrow{x_n}; \\ \vdots \\ \overleftarrow{x_{S_1}} \oplus \stackrel{\triangle}{=} \overline{x_1} \overleftarrow{x_1} \\ \text{in } \overleftarrow{x_0} \text{ end})) \text{ end} \end{array} \right\}$$

# The Functional Reverse-Mode Transformation

$$\left. \begin{array}{l} \lambda x_0 \text{ let } x_1 \stackrel{\triangle}{=} x_{R_1} x_{S_1}; \\ \vdots \\ x_n \stackrel{\triangle}{=} x_{R_n} x_{S_n} \\ \text{in } x_n \text{ end} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \lambda \overleftarrow{x_0} \text{ let } (\overleftarrow{x_1}, \overline{x_1}) \stackrel{\triangle}{=} \overleftarrow{x_{R_1}} \overleftarrow{x_{S_1}}; \\ \vdots \\ (\overleftarrow{x_n}, \overline{x_n}) \stackrel{\triangle}{=} \overleftarrow{x_{R_n}} \overleftarrow{x_{S_n}} \\ \text{in } (\overleftarrow{x_n}, (\lambda \overleftarrow{x_n} \text{ let } \overleftarrow{x_0} \stackrel{\triangle}{=} \mathbf{0} (\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x_0})) \text{ end} \\ \vdots \\ \overleftarrow{x_{n-1}} \stackrel{\triangle}{=} \mathbf{0} (\overleftarrow{\mathcal{J}}^{-1} \overleftarrow{x_{n-1}}); \\ \overleftarrow{x_{S_n}} \oplus \stackrel{\triangle}{=} \overline{x_n} \overleftarrow{x_n}; \\ \vdots \\ \overleftarrow{x_{S_1}} \oplus \stackrel{\triangle}{=} \overline{x_1} \overleftarrow{x_1} \\ \text{in } \overleftarrow{x_0} \text{ end})) \text{ end} \end{array} \right\}$$

The above is a white lie. The truth is a lot more complicated.

# Modularity

$$\nabla f \mathbf{x} \triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

# Modularity

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$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

# Modularity

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$$\operatorname{argmin} f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

# Modularity

$$\nabla f \mathbf{x} \triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

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$$\begin{aligned} \text{argmin } f &\triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots \\ \text{NEUTRONFLUX } r &\triangleq \boxed{\textit{classified}} \end{aligned}$$

# Modularity

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$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

# Modularity

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$$r^* \triangleq \text{argmin } \text{DEVIATION}$$

Fermi, E. (1946). *The Development of the first chain reaction pile.*  
Proceedings of the American Philosophy Society, 90:20–4.

# Breaking Modularity

$$\nabla f \mathbf{x} \triangleq (\overrightarrow{f} \mathbf{x} \triangleright \overrightarrow{\mathbf{e}_1}), \dots, (\overrightarrow{f} \mathbf{x} \triangleright \overrightarrow{\mathbf{e}_n})$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

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$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\operatorname{argmin} f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

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# Breaking Modularity

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$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\operatorname{argmin} f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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# Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \overrightarrow{\mathbf{e}_1}), \dots, (\vec{f} \mathbf{x} \triangleright \overrightarrow{\mathbf{e}_n})$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\operatorname{argmin} f \triangleq \dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\textit{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$r^* \triangleq \operatorname{argmin} \text{DEVIATION}$$

Fermi, E. (1946). *The Development of the first chain reaction pile.*  
Proceedings of the American Philosophy Society, 90:20–4.

# Breaking Modularity

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$$\operatorname{argmin} \overleftarrow{f}$$

$$\triangleq \dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r}$$

$$\triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{NEUTRONFLUX}}$$

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$$\triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r}$$

$$\triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{DEVIATION}}$$

$$\mathbf{r}^* \triangleq \operatorname{argmin} \overleftarrow{\text{DEVIATION}}$$

Fermi, E. (1946). *The Development of the first chain reaction pile.*  
Proceedings of the American Philosophy Society, 90:20–4.

# Breaking Modularity

$$\nabla \overleftarrow{f} \mathbf{x}$$

$$\triangleq \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\mathcal{H} \overrightarrow{\overleftarrow{f}} \mathbf{x}$$

$$\triangleq \dots \overrightarrow{\overleftarrow{f}} \dots \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0$$

$$\triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{NEWTONSMETHOD } \overleftarrow{f} \overrightarrow{\overleftarrow{f}} \mathbf{x}_0$$

$$\triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{\overleftarrow{f}} \mathbf{x}_i \dots$$

$$\operatorname{argmin} \overleftarrow{f}$$

$$\triangleq \dots \text{NEWTONSMETHOD } \overleftarrow{f} \overrightarrow{\overleftarrow{f}} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r}$$

$$\triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r}$$

$$\triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{DEVIATION}}$$

$$\mathbf{r}^*$$

$$\triangleq \operatorname{argmin} \overleftarrow{\text{DEVIATION}}$$

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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
$\text{argmin } \overleftarrow{f} \overrightarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<div style="border: 1px solid black; padding: 2px;"><i>classified</i></div>
NEUTRONFLUX	TAPENADE $\rightsquigarrow$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	TAPENADE $\rightsquigarrow$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	$\text{argmin } \overleftarrow{\text{DEVIATION}}$

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# Breaking Modularity

$$\nabla \overleftarrow{f} \mathbf{x}$$

$$\triangleq \dots \overleftarrow{f} \mathbf{x} \dots$$

$$\mathcal{H} \overrightarrow{\overleftarrow{f}} \mathbf{x}$$

$$\triangleq \dots \overrightarrow{\overleftarrow{f}} \dots \mathbf{x} \dots$$

$$\text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0$$

$$\triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$$

$$\text{NEWTONSMETHOD } \overleftarrow{f} \overrightarrow{\overleftarrow{f}} \mathbf{x}_0$$

$$\triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{\overleftarrow{f}} \mathbf{x}_i \dots$$

$$\operatorname{argmin} \overleftarrow{f} \overrightarrow{\overleftarrow{f}}$$

$$\triangleq \dots \text{NEWTONSMETHOD } \overleftarrow{f} \overrightarrow{\overleftarrow{f}} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r}$$

$$\triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r}$$

$$\triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\text{DEVIATION}$$

$$\begin{array}{c} \text{TAPENADE} \\ \rightsquigarrow \end{array} \overleftarrow{\text{DEVIATION}}$$

$$\mathbf{r}^*$$

$$\triangleq \operatorname{argmin} \overleftarrow{\text{DEVIATION}} \overleftarrow{\overleftarrow{\text{DEVIATION}}}$$

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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
$\text{argmin } \overleftarrow{f} \overrightarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<div style="border: 1px solid black; padding: 2px;"><i>classified</i></div>
NEUTRONFLUX	TAPENADE $\rightsquigarrow$	$\overleftarrow{\text{NEUTRONFLUX}}$
$\overleftarrow{\text{NEUTRONFLUX}}$	TAPENADE $\rightsquigarrow$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	TAPENADE $\rightsquigarrow$	$\overleftarrow{\text{DEVIATION}}$
$\overleftarrow{\text{DEVIATION}}$	TAPENADE $\rightsquigarrow$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	$\text{argmin } \overleftarrow{\text{DEVIATION}} \overleftarrow{\text{DEVIATION}}$

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# Restoring Modularity

$\nabla f \mathbf{x}$	$\triangleq$	
$\mathcal{H}f \mathbf{x}$	$\triangleq$	
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H}f \mathbf{x}_i \dots$
$\operatorname{argmin} f$	$\triangleq$	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<div style="border: 1px solid black; padding: 2px;"><i>classified</i></div>
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
$\mathbf{r}^*$	$\triangleq$	$\operatorname{argmin} \text{ DEVIATION}$

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# Restoring Modularity

$$\nabla f \mathbf{x} \triangleq ((\xrightarrow{\mathcal{J}} f) \mathbf{x} \triangleright \overline{\mathbf{e}_1}), \dots, ((\xrightarrow{\mathcal{J}} f) \mathbf{x} \triangleright \overline{\mathbf{e}_n})$$

$$\mathcal{H} f \mathbf{x} \triangleq$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

$$\text{NEWTONSMETHOD } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$$

$$\operatorname{argmin} f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r} \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } \mathbf{r} \triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\mathbf{r}^* \triangleq \operatorname{argmin} \text{ DEVIATION}$$

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# Restoring Modularity

$$\nabla f \mathbf{x} \triangleq \dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$$

$$\mathcal{H} f \mathbf{x} \triangleq$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

$$\text{NEWTONSMETHOD } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$$

$$\operatorname{argmin} f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } \mathbf{r} \triangleq \boxed{\textit{classified}}$$

$$\text{DEVIATION } \mathbf{r} \triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$\mathbf{r}^* \triangleq \operatorname{argmin} \text{ DEVIATION}$$

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# Restoring Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	$\triangleq$	$\dots (\overrightarrow{\mathcal{J}} (\overleftarrow{\mathcal{J}} f)) \dots \mathbf{x} \dots$
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
$\operatorname{argmin} f$	$\triangleq$	$\dots \text{NEWTONSMETHOD } f \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<div style="border: 1px solid black; padding: 2px;"><i>classified</i></div>
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
$\mathbf{r}^*$	$\triangleq$	$\operatorname{argmin} \text{ DEVIATION}$

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# Having your cake and eating it too

- Convenient
- Fast

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  - $\mathcal{D}$  formulated as a higher-order function in the language
- Fast

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- Convenient
  - $\mathcal{D}$  formulated as a higher-order function in the language
  - no arbitrary restrictions
    - applies to all data types and constructs in the language, including code produced by  $\mathcal{D}$  and even  $\mathcal{D}$  itself
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  - higher-order derivatives  
 $(\mathcal{D} \ (\mathcal{D} \ f))$
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- $\mathcal{D}$  formulated as a higher-order function in the language
- no arbitrary restrictions
  - applies to all data types and constructs in the language, including code produced by  $\mathcal{D}$  and even  $\mathcal{D}$  itself
- higher-order derivatives
  - $(\mathcal{D} (\mathcal{D} f))$
- nesting
  - $(\mathcal{D} (\lambda (...) \dots (\mathcal{D} (\lambda (...) \dots) \dots) \dots))$

- Fast

# Having your cake and eating it too

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  - $\mathcal{D}$  formulated as a higher-order function in the language
  - no arbitrary restrictions
    - applies to all data types and constructs in the language, including code produced by  $\mathcal{D}$  and even  $\mathcal{D}$  itself
  - higher-order derivatives  
 $(\mathcal{D} (\mathcal{D} f))$
  - nesting  
 $(\mathcal{D} (\lambda (...) \dots (\mathcal{D} (\lambda (...) \dots) \dots) \dots))$
- Fast
  - $\mathcal{D}$  implemented by reflective transformation of environments and code associated with closures

# Having your cake and eating it too

- Convenient
  - $\mathcal{D}$  formulated as a higher-order function in the language
  - no arbitrary restrictions
    - applies to all data types and constructs in the language, including code produced by  $\mathcal{D}$  and even  $\mathcal{D}$  itself
  - higher-order derivatives
$$(\mathcal{D} (\mathcal{D} f))$$
  - nesting
$$(\mathcal{D} (\lambda (...) \dots (\mathcal{D} (\lambda (...) \dots) \dots) \dots))$$
- Fast
  - $\mathcal{D}$  implemented by reflective transformation of environments and code associated with closures
  - compile away reflection with partial evaluation implemented by flow analysis

# Monovariant Flow Analysis: 0-CFA

```
(define (D f)
  ...)
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f)
  ...)
(D (lambda (x) 2x3))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x³))  
...)
```

```
(D (lambda (x) 2x³))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x3))  
...:(λx 6x2))
```

```
(D (lambda (x) 2x3))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x3))  
...:(λx 6x2))
```

```
(D (lambda (x) 2x3)):(λx 6x2)
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x3))  
...:(λx 6x2))
```

```
(D (lambda (x) 2x3)):(λx 6x2)
```

```
(D (lambda (x) 3x4))
```

# Monovariant Flow Analysis: 0-CFA

(define ( $\mathcal{D}$  f : $(\lambda x 2x^3) \cup (\lambda x 3x^4)$ )

... : $(\lambda x 6x^2)$ )

( $\mathcal{D}$  ( $\lambda$  (x)  $2x^3$ )) : $(\lambda x 6x^2)$

( $\mathcal{D}$  ( $\lambda$  (x)  $3x^4$ ))

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x3) ∪ (λx 3x4) )
```

```
...:(λx 6x2) ∪ (λx 12x3) )
```

```
(D (lambda (x) 2x3) ):(λx 6x2)
```

```
(D (lambda (x) 3x4) )
```

# Monovariant Flow Analysis: 0-CFA

(define ( $\mathcal{D}$  f :  $(\lambda x \ 2x^3) \cup (\lambda x \ 3x^4)$ ) )

... :  $(\lambda x \ 6x^2) \cup (\lambda x \ 12x^3)$ ) )

$(\mathcal{D} \ (\lambda x \ 2x^3)) : (\lambda x \ 6x^2)$

$(\mathcal{D} \ (\lambda x \ 3x^4)) : (\lambda x \ 12x^3)$

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx 2x3) ∪ (λx 3x4) )  
...:(λx 6x2) ∪ (λx 12x3) )
```

```
(D (lambda (x) 2x3) ):(λx 6x2) ∪ (λx 12x3)
```

```
(D (lambda (x) 3x4) ):(λx 6x2) ∪ (λx 12x3)
```

# Monovariant Flow Analysis: 0-CFA

(define ( $\mathcal{D}$  f:( $\lambda x 2x^3$ )  $\cup$  ( $\lambda x 3x^4$ ))

...:( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ ))

( $\mathcal{D}$  ( $\lambda$  (x)  $2x^3$ )) : ( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ )

( $\mathcal{D}$  ( $\lambda$  (x)  $3x^4$ )) : ( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ )

# Monovariant Flow Analysis: 0-CFA

```
(define (D f)
  ...)
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f)
  ...)
(D (D (lambda (x) e2x)))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x) )  
  ...)  
  
(D (D (lambda (x) e2x)) )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x) )
      ...:(λx 2e2x) )

(D (D (lambda (x) e2x) ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x))  
...:(λx 2e2x))
```

```
(D (D (lambda (x) e2x)):(λx 2e2x))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f :((λx e2x) ∪ (λx 2e2x))  
... :(λx 2e2x))
```

```
(D (D (lambda (x) e2x)) :(λx 2e2x))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x) ∪ (λx 2e2x) )  
  ...:(λx 2e2x) ∪ (λx 4e2x) )
```

```
(D (D (lambda (x) e2x) ):(λx 2e2x) )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x) ∪ (λx 2e2x) )  
  ...:(λx 2e2x) ∪ (λx 4e2x) )
```

```
(D (D (lambda (x) e2x) ):(λx 2e2x) ∪ (λx 4e2x) )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x) ∪ (λx 2e2x) ∪ (λx 4e2x))  
...:(λx 2e2x) ∪ (λx 4e2x))
```

```
(D (D (lambda (x) e2x)):(λx 2e2x) ∪ (λx 4e2x))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f : (λx e2x) ∪ (λx 2e2x) ∪ (λx 4e2x) ∪ ...)  
  ... : (λx 2e2x) ∪ (λx 4e2x) ∪ ...)
```

```
(D (D (lambda (x) e2x)) : (λx 2e2x) ∪ (λx 4e2x) ∪ ...)
```

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (D f) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (D f) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (g ...) ... (D (lambda (x) 2x3)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

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```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (Dh f) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (Dh f:(λx 3x4)) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (Dh f:(λx 3x4)) ...:(λx 12x3) )
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

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```
(define (Dg f:(λx 2x3)) ...:(λx 6x2) )
```

```
(define (Dh f:(λx 3x4)) ...:(λx 12x3) )
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)):(λx 12x3) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x)))))
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x)))))

((compose k D) g)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

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(define ((compose n f) x)
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⋮
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No tags, tag checking, tag dispatching, indirect calls

Allows complete unboxing: no allocation, reclamation, indirection

# Game Theory

		$B$				
		$b_1$	$\dots$	$b_j$	$\dots$	$b_n$
$A$		$a_1$				
		$\vdots$	$\ddots$		$\vdots$	
$a_i$			$\dots$	$\text{PAYOFF}(a_i, b_j)$	$\dots$	
$a_m$				$\vdots$		$\ddots$

von Neumann, J. and Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press, Princeton, NJ.

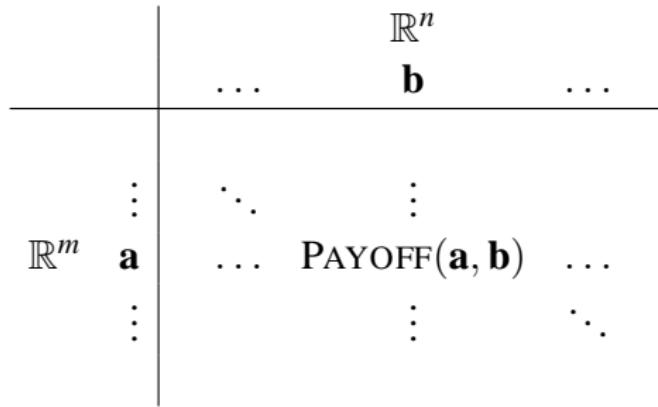
# Game Theory

		$B$				
		$b_1$	$\dots$	$b_j$	$\dots$	$b_n$
$A$		$a_1$				
		$\vdots$	$\ddots$		$\vdots$	
$a_i$			$\dots$	$\text{PAYOFF}(a_i, b_j)$	$\dots$	
$a_m$				$\vdots$		$\ddots$

$$\max_{a \in A} \min_{b \in B} \text{PAYOFF}(a, b)$$

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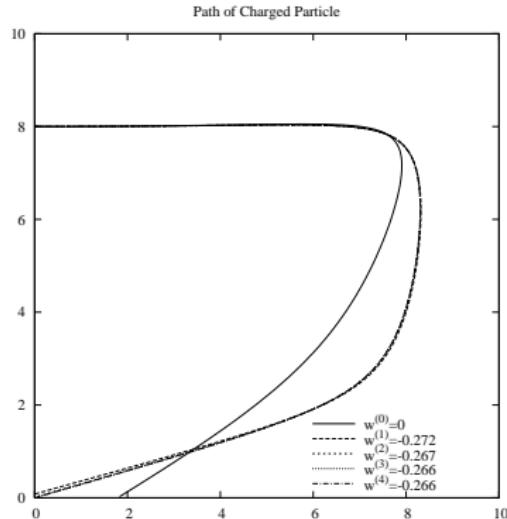
# Game Theory



$$\max_{\mathbf{a} \in \mathbb{R}^m} \min_{\mathbf{b} \in \mathbb{R}^n} \text{PAYOFF}(\mathbf{a}, \mathbf{b})$$

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# Cathode Ray Tubes



$$\text{potential: } p(\mathbf{x}; w) = \|\mathbf{x} - (10, 10 - w)\|^{-1} + \|\mathbf{x} - (10, 0)\|^{-1}$$

$$\ddot{\mathbf{x}}(t) = -\nabla_{\mathbf{x}} p(\mathbf{x})|_{\mathbf{x}=\mathbf{x}(t)}$$

$$\dot{\mathbf{x}}(t + \Delta t) = \dot{\mathbf{x}}(t) + \Delta t \ddot{\mathbf{x}}(t)$$

$$\mathbf{x}(t + \Delta t) = \mathbf{x}(t) + \Delta t \dot{\mathbf{x}}(t)$$

$$\text{When: } x_1(t + \Delta t) \leq 0$$

$$\text{let: } \Delta t_f = -x_1(t)/\dot{x}_1(t)$$

$$t_f = t + \Delta t_f$$

$$\mathbf{x}(t_f) = \mathbf{x}(t) + \Delta t_f \dot{\mathbf{x}}(t)$$

$$\text{Error: } E(w) = x_0(t_f)^2$$

$$\text{Find: } \underset{w}{\operatorname{argmin}} E(w)$$

Sprague, C. S. and George, R. H. (1939). *Cathode Ray Deflecting Electrode*. US Patent 2,161,437.

George, R. H. (1940). *Cathode Ray Tube*. US Patent 2,222,942.

# Performance Comparison

		particle				saddle			
		FF	FR	RF	RR	FF	FR	RF	RR
VLAD	STALIN $\nabla$	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
FORTRAN	ADIFOR	1.52	■	■	■	2.07	■	■	■
	TAPENADE	3.40	■	■	■	2.56	■	■	■
C++	FADBADD++	65.69	■	■	■	22.44	■	■	■
ML	MLTON	53.89	88.88	16.08	28.06	40.39	51.21	1.86	2.67
	OCAML	160.50	340.35	147.91	263.66	107.71	156.33	6.75	13.51
	SML/NJ	106.21	182.45	105.04	185.15	84.38	106.01	3.55	6.31
HASKELL	GHC	165.22	■	■	■	121.18	■	■	■
SCHEME	BIGLOO	505.90	761.40	104.81	228.56	423.69	440.25	15.77	24.59
	CHICKEN	1120.37	2026.31	425.60	1872.85	889.58	1144.65	35.73	68.94
	GAMBIT	444.13	752.63	138.34	256.30	362.65	420.48	14.08	23.87
	IKARUS	192.07	312.28	61.79	114.87	158.88	205.97	6.75	11.40
	LARCENCY	726.59	1108.18	144.55	270.14	571.81	613.65	19.14	29.77
	MIT SCHEME	1472.26	2500.00	309.66	591.36	1243.26	1428.57	51.36	79.10
	MzC	2073.26	3434.64	340.30	655.83	2436.26	1996.40	72.45	150.02
	MZSCHEME	2344.70	4076.16	409.95	843.68	2000.89	2332.43	80.78	134.00
	SCHEME->C	391.42	605.26	109.77	198.43	324.95	328.84	12.74	18.28
	SCMUTILS	3321.20	■	■	■	2800.71	■	■	■
	STALIN	208.10	366.08	51.84	91.86	166.96	212.93	7.68	11.40

- not implemented but could implement
- not implemented in existing tool
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# Gradient-Based Optimization

```
(define (e i n)
  (if (zero? n)
      '()
      (cons (if (zero? i) 1.0 0.0)
            (e (- i 1) (- n 1))))))
```

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```
(define (e i n)
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(define ((gradient f) x)
  (let ((n (length x)))
    (map (lambda (i) (tangent ((j* f) (bundle x (e i n))))))
         (iota n))))
```

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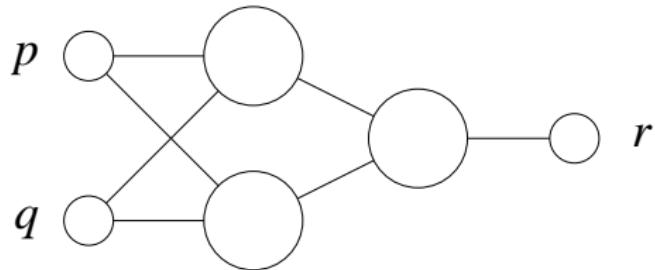
(define ((gradient f) x)
  (let ((n (length x)))
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          (iota n)))

(define (gradient-ascent f x0 n eta)
  (if (zero? n)
      (list x0 (f x0) ((gradient f) x0))
      (gradient-ascent f
                        (zip (lambda (xi gi) (+ xi (* eta gi)))
                             x0
                             ((gradient f) x0))
                        (- n 1)
                        eta)))
```

# Gradient-Based Optimization

```
(define ((gradient f) x) (cdr ((cdr ((*j f) (*j x))) 1.0)))  
  
(define (gradient-ascent f x0 n eta)  
  (if (zero? n)  
      (list x0 (f x0) ((gradient f) x0))  
      (gradient-ascent f  
                      (zip (lambda (xi gi) (+ xi (* eta gi)))  
                            x0  
                            ((gradient f) x0))  
                      (- n 1)  
                      eta))))
```

# Neural Networks



$p$	$q$	$r$
0	0	0
0	1	1
1	0	1
1	1	0

Rumelhart, D. E., Hinton, G. E., and Williams, R. J. (1986). *Learning representations by back-propagating errors*. Nature, **323**:533–6.

# Neural Networks in VLAD

```
(define ((sum-activities activities) bias ws)
  ((fold + bias) (zip * ws activities)))
```

# Neural Networks in VLAD

```
(define ((sum-activities activities) bias ws)
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(define (sum-layer activities ws-layer)
  (map (sum-activities activities) ws-layer))
```

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(define (sigmoid x) (/ 1 (+ (exp (- 0 x)) 1)))
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(define ((forward-pass ws-layers) in)
  (if (null? ws-layers)
      in
      ((forward-pass (cdr ws-layers))
       (map sigmoid (sum-layer in (car ws-layers))))))
```

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(define ((error-on-dataset dataset) ws-layers)
  ((fold + 0)
   (map (lambda ((list in target))
          (* 0.5 (magnitude-squared (v- ((forward-pass ws-layers) in) target))))
        dataset)))
```

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        dataset)))

(gradient-descent (error-on-dataset '(((0 0) (0))
                                         ((0 1) (1))
                                         ((1 0) (1))
                                         ((1 1) (0))))
                  '(((0 -0.284227 1.16054) (0 0.617194 1.30467))
                    ((0 -0.084395 0.648461)))
                  1000.0
                  0.3))
```

# Performance Comparison

		backprop		
		Fs	Fv	R
VLAD	STALIN $\nabla$	1.00	■	1.00
FORTRAN	ADIFOR	11.84	2.68	■
	TAPENADE	11.35	4.33	6.24
C	ADIC	16.33	3.93	■
C++	ADOL-C	12.34	3.89	35.53
	CPPAD	42.15	■	23.69
	FADBAD++	98.96	33.15	53.03
ML	MLTON	73.94	■	37.94
	OCAML	157.75	■	149.14
	SML/NJ	142.71	■	94.97
HASKELL	GHC	■	■	■
SCHEME	BIGLOO	577.45	■	306.60
	CHICKEN	1391.75	■	971.91
	GAMBIT	545.20	■	341.73
	IKARUS	216.42	■	147.49
	LARCENCY	955.98	■	486.64
	MIT SCHEME	1900.04	■	1141.22
	MzC	2439.93	■	1571.52
	MZSCHEME	3477.86	■	1866.28
	SCHEME->C	484.24	■	233.75
	SCMUTILS	4544.48	■	■
	STALIN	832.68	■	367.84

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# Probabilistic Lambda Calculus

$P = \text{if } x_0 \text{ then } 0 \text{ else if } x_1 \text{ then } 1 \text{ else } 2$

Koller, D., McAllester, D. , and Pfeffer, A. (1997). *Effective Bayesian Inference for Stochastic Programs*. Proceedings of the 14th National Conference on Artificial Intelligence (AAAI), pp. 740–7.

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$$\Pr(x_1 \mapsto \mathbf{true}) = p_1$$

$$\Pr(x_0 \mapsto \mathbf{false}) = 1 - p_0$$

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$$\Pr(\mathcal{E}(P) = 0 | p_0, p_1) = p_0$$

$$\Pr(\mathcal{E}(P) = 1 | p_0, p_1) = (1 - p_0)p_1$$

$$\Pr(\mathcal{E}(P) = 2 | p_0, p_1) = (1 - p_0)(1 - p_1)$$

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$$\Pr(\mathcal{E}(P) = 2 | p_0, p_1) = (1 - p_0)(1 - p_1)$$

$$\prod_{v \in \{0,1,2,2\}} \Pr(\mathcal{E}(P) = v | p_0, p_1) = p_0(1 - p_0)^3 p_1(1 - p_1)^2$$

Koller, D., McAllester, D. , and Pfeffer, A. (1997). *Effective Bayesian Inference for Stochastic Programs*. Proceedings of the 14th National Conference on Artificial Intelligence (AAAI), pp. 740–7.

# Probabilistic Lambda Calculus

$P = \text{if } x_0 \text{ then } 0 \text{ else if } x_1 \text{ then } 1 \text{ else } 2$

$$\Pr(x_0 \mapsto \mathbf{true}) = p_0$$

$$\Pr(x_1 \mapsto \mathbf{true}) = p_1$$

$$\Pr(x_0 \mapsto \mathbf{false}) = 1 - p_0$$

$$\Pr(x_1 \mapsto \mathbf{false}) = 1 - p_1$$

$$\Pr(\mathcal{E}(P) = 0 | p_0, p_1) = p_0$$

$$\Pr(\mathcal{E}(P) = 1 | p_0, p_1) = (1 - p_0)p_1$$

$$\Pr(\mathcal{E}(P) = 2 | p_0, p_1) = (1 - p_0)(1 - p_1)$$

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$$\operatorname{argmax}_{p_0, p_1} \prod_{v \in \{0,1,2,2\}} \Pr(\mathcal{E}(P) = v | p_0, p_1) = \left\langle \frac{1}{4}, \frac{1}{3} \right\rangle$$

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# Probabilistic Prolog

```
p(0).  
p(X):-q(X).  
q(1).  
q(2).
```

# Probabilistic Prolog

$$\Pr(p(0) .) = p_0$$

$$\Pr(p(X) :- \neg q(X) .) = 1 - p_0$$

$$\Pr(q(1) .) = p_1$$

$$\Pr(q(2) .) = 1 - p_1$$

# Probabilistic Prolog

$$\Pr(p(0).) = p_0$$

$$\Pr(p(X) :- q(X).) = 1 - p_0$$

$$\Pr(q(1).) = p_1$$

$$\Pr(q(2).) = 1 - p_1$$

$$\Pr(?-p(0).) = p_0$$

$$\Pr(?-p(1).) = (1 - p_0)p_1$$

$$\Pr(?-p(2).) = (1 - p_0)(1 - p_1)$$

# Probabilistic Prolog

$$\Pr(p(0).) = p_0$$

$$\Pr(p(X) :- \neg q(X).) = 1 - p_0$$

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$$\Pr(q(2).) = 1 - p_1$$

$$\Pr(\neg p(0).) = p_0$$

$$\Pr(\neg p(1).) = (1 - p_0)p_1$$

$$\Pr(\neg p(2).) = (1 - p_0)(1 - p_1)$$

$$\prod_{q \in \{p(0), p(1), p(2), \neg p(2)\}} \Pr(\neg q.) = p_0(1 - p_0)^3 p_1(1 - p_1)^2$$

# Probabilistic Prolog

$$\Pr(p(0).) = p_0$$

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# Probabilistic Lambda Calculus

```
(define (evaluate expression environment)
  (cond
    ((constant-expression? expression)
     (singleton-tagged-distribution
      (constant-expression-value expression)))
    ((variable-access-expression? expression)
     (lookup-value
      (variable-access-expression-variable expression) environment))
    ((lambda-expression? expression)
     (singleton-tagged-distribution
      (lambda (tagged-distribution)
        (evaluate
          (lambda-expression-body expression)
          (cons (make-binding (lambda-expression-variable expression)
                            tagged-distribution)
                environment))))))
    (else (let ((tagged-distribution
                 (evaluate (application-argument expression)
                           environment)))
            (map-tagged-distribution
              (lambda (value) (value tagged-distribution))
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```

# Probabilistic Lambda Calculus

```
(gradient-ascent
  (lambda (p)
    (let ((tagged-distribution
           (evaluate if  $x_0$  then 0 else
                    if  $x_1$  then 1 else 2
                     (list  $\Pr(x_0 \mapsto \text{true}) = p_0$   $\Pr(x_0 \mapsto \text{false}) = 1 - p_0$ 
                            $\Pr(x_1 \mapsto \text{true}) = p_1$   $\Pr(x_1 \mapsto \text{false}) = 1 - p_1$ 
                           ...)))
      (map-reduce
        *
        1.0
        (lambda (value)
          (likelihood value tagged-distribution))
        '(0 1 2 2)))
      '(0.5 0.5)
      1000.0
      0.1))
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```

# Probabilistic Prolog

```
(define (proof-distribution term clauses)
  (let ((offset ...))
    (map-reduce
      append
      '()
      (lambda (clause)
        (let ((clause (alpha-rename clause offset)))
          (let loop ((p (clause-p clause))
                    (substitution (unify term (clause-term clause)))
                    (terms (clause-terms clause)))
            (if (boolean? substitution)
                '()
                (if (null? terms)
                    (list (make-double p substitution))
                    (map-reduce
                      append
                      '()
                      (lambda (double)
                        (loop (* p (double-p double))
                          (append substitution (double-substitution double))
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                (if (null? terms)
                    (list (make-double p substitution))
                    (map-reduce
                      append
                      '()
                      (lambda (double)
                        (loop (* p (double-p double))
                          (append substitution (double-substitution double))
                          (rest terms)))
                      (proof-distribution
                        (apply-substitution substitution (first terms)) clauses)))))))
          clauses))))
```

# Probabilistic Prolog

```
(define (proof-distribution term clauses)
  (let ((offset ...))
    (map-reduce
      append
      '()
      (lambda (clause)
        (let ((clause (alpha-rename clause offset)))
          (let loop ((p (clause-p clause))
                    (substitution (unify term (clause-term clause)))
                    (terms (clause-terms clause)))
            (if (boolean? substitution)
                '()
                (if (null? terms)
                    (list (make-double p substitution))
                    (map-reduce
                      append
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                      (lambda (double)
                        (loop (* p (double-p double))
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                      (proof-distribution
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          clauses))))
```

# Probabilistic Prolog

```
(gradient-ascent
  (lambda (p)
    (let ((clauses (list Pr(p(0).) = p0
                           Pr(p(X):-q(X).) = 1 - p0
                           Pr(q(1).) = p1
                           Pr(q(2).) = 1 - p1)))
      (map-reduce
        *
        1.0
        (lambda (query)
          (likelihood (proof-distribution query clauses)))
        '(p(0) p(1) p(2) p(2))))
      '(0.5 0.5)
      1000.0
      0.1))
```

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        *
        1.0
        (lambda (query)
          (likelihood (proof-distribution query clauses)))
        '(p(0) p(1) p(2) p(2))))
      '(0.5 0.5)
      1000.0
      0.1))
```

# Probabilistic Prolog

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        *
        1.0
        (lambda (query)
          (likelihood (proof-distribution query clauses)))
        '(p(0) p(1) p(2) p(2))))
      '(0.5 0.5)
      1000.0
      0.1))
```

# Generated Code

```
static void f2679(double a_f2679_0,double a_f2679_1,double a_f2679_2,double a_f2679_3){  
    int t272381=((a_f2679_2==0.)?0:1);  
    double t272406;  
    double t272405;  
    double t272404;  
    double t272403;  
    double t272402;  
    if((t272381==0)){  
        double t272480=(1.-a_f2679_0);  
        double t272572=(1.-a_f2679_1);  
        double t273043=(a_f2679_0+0.);  
        double t274185=(t272480*a_f2679_1);  
        double t274426=(t274185+0.);  
        double t275653=(t272480*t272572);  
        double t275894=(t275653+0.);  
        double t277121=(t272480*t272572);  
        double t277362=(t277121+0.);  
        double t277431=(t277362*1.);  
        double t277436=(t275894*t277431);  
        double t277441=(t274426*t277436);  
        double t277446=(t273043*t277441);  
        ...  
        double t1777107=(t1774696+t1715394);  
        double t1777194=(0.-t1745420);  
        double t1778533=(t1777194+t1419700);  
        t272406=a_f2679_0;  
        t272405=a_f2679_1;  
        t272404=t277446;  
        t272403=t1778533;  
        t272402=t1777107;}  
    else {...}  
    r_f2679_0=t272406;  
    r_f2679_1=t272405;  
    r_f2679_2=t272404;  
    r_f2679_3=t272403;  
    r_f2679_4=t272402;}
```

# Performance Comparison

		probabilistic-lambda-calculus		probabilistic-prolog	
		F	R	F	R
VLAD	STALIN $\nabla$	1.00	1.00	1.00	1.00
ML	MLTON	106.45	124.95	789.41	483.47
	OCAML	215.73	538.68	1207.13	1534.61
	SML/NJ	197.75	272.45	2448.02	1471.94
HASKELL	GHC	■	■	■	■
SCHEME	BIGLOO	832.92	1048.11	14422.16	8286.06
	CHICKEN	2305.98	3283.00	66948.70	37792.84
	GAMBIT	879.88	1153.86	24316.03	13649.81
	IKARUS	437.46	531.10	8242.92	4845.86
	LARCENCY	1651.01	1673.22	25589.62	14833.53
	MIT SCHEME	3491.10	4130.19	85819.57	48335.38
	MZC	5289.17	5929.14	154206.95	83480.27
	MZSCHEME	6235.78	7134.71	166129.12	91630.70
	SCHEME->C	682.15	794.31	10530.66	5980.27
	SCMUTILS	6456.99	■	80100.23	■
	STALIN	1240.73	1137.41	22511.79	10986.43

- not implemented but could implement, including FORTRAN, C, and C++
- not implemented in existing tool
- can't implement

*It is, of course, not excluded that the range of arguments or range of values of a function should consist wholly or partly of functions. The derivative, as this notion appears in the elementary differential calculus, is a familiar mathematical example of a function for which both ranges consist of functions.*

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