

#### **GPU Teaching Kit**

**Accelerated Computing** 



Lecture 20 – Related Programming Models: OpenCL

Lecture 20.1 - OpenCL Data Parallelism Model

# Objective

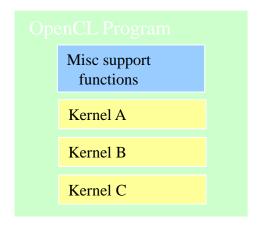
- To Understand the OpenCL programming model
  - basic concepts and data types
  - Kernel structure
  - Application programming interface
  - Simple examples

# Background

- OpenCL was initiated by Apple and maintained by the Khronos Group (also home of OpenGL) as an industry standard API
  - For cross-platform parallel programming in CPUs, GPUs, DSPs, FPGAs,...
- OpenCL draws heavily on CUDA
  - Easy to learn for CUDA programmers
- OpenCL host code is much more complex and tedious due to desire to maximize portability and to minimize burden on vendors

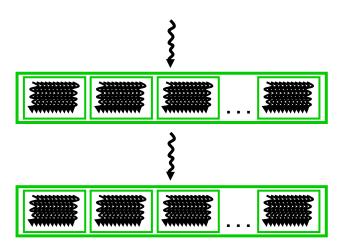
# **OpenCL Programs**

- An OpenCL "program" is a C program that contains one or more "kernels" and any supporting routines that run on a target device
- An OpenCL kernel is the basic unit of parallel code that can be executed on a target device



# **OpenCL Execution Model**

- Integrated host+device app C program
  - Serial or modestly parallel parts in host C code
  - Highly parallel parts in device SPMD kernel C code



# Mapping between OpenCL and CUDA data parallelism model concepts.

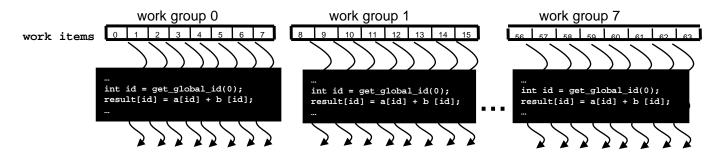
OpenCL Parallelism Concept	CUDA Equivalent
host	host
device	device
kernel	kernel
host program	host program
NDRange (index space)	grid
work item	thread
work group	block

# OpenCL Kernels

- Code that executes on target devices
- Kernel body is instantiated once for each work item
  - An OpenCL work item is equivalent to a CUDA thread
- Each OpenCL work item gets a unique index

### Array of Work Items

- An OpenCL kernel is executed by an array of work items
  - All work items run the same code (SPMD)
  - Each work item can call get\_global\_id() to get its index for computing memory addresses and make control decisions



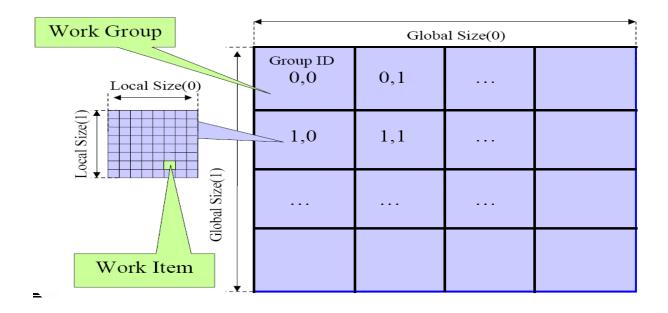
# Work Groups: Scalable Cooperation

- Divide monolithic work item array into work groups
  - Work items within a work group cooperate via shared memory and barrier synchronization
  - Work items in different work groups cannot cooperate
- OpenCL counter part of CUDA Thread Blocks

# OpenCL Dimensions and Indices

OpenCL API Call	Explanation	CUDA Equivalent
get_global_id(0);	global index of the work item in the x dimension	blockldx.x*blockDim.x +threadldx.x
get_local_id(0)	local index of the work item within the work group in the x dimension	threadldx.x
get_global_size(0);	size of NDRange in the x dimension	gridDim.x*blockDim.x
get_local_size(0);	Size of each work group in the x dimension	blockDim.x

# Multidimensional Work Indexing



# OpenCL Data Parallel Model Summary

- Parallel work is submitted to devices by launching kernels
- Kernels run over global dimension index ranges (NDRange), broken up into "work groups", and "work items"
- Work items executing within the same work group can synchronize with each other with barriers or memory fences
- Work items in different work groups can't sync with each other, except by terminating the kernel



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Module 20 – Related Programming Models: OpenCL

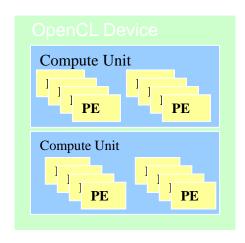
Lecture 20.2 - OpenCL Device Architecture

# Objective

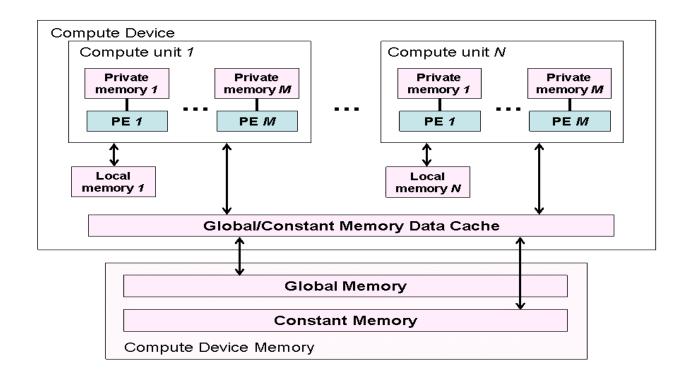
- To Understand the OpenCL device architecture
  - Foundation to terminology used in the host code
  - Also needed to understand the memory model for kernels

### **OpenCL Hardware Abstraction**

- OpenCL exposes CPUs, GPUs, and other Accelerators as "devices"
- Each device contains one or more "compute units", i.e. cores, Streaming Multicprocessors, etc...
- Each compute unit contains one or more SIMD "processing elements", (i.e. SP in CUDA)



# **OpenCL Device Architecture**

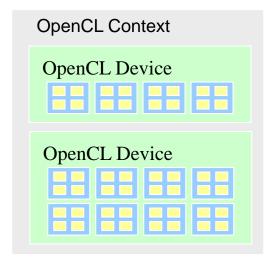


# OpenCL Device Memory Types

Memory Type	Host access	Device access	CUDA Equivalent
global memory	Dynamic allocation; Read/write access	No allocation; Read/write access by all work items in all work groups, large and slow but may be cached in some devices.	global memory
constant memory	Dynamic allocation; read/write access	Static allocation; read-only access by all work items.	constant memory
local memory	Dynamic allocation; no access	Static allocation; shared read-write access by all work items in a work group.	shared memory
private memory	No allocation; no access	Static allocation; Read/write access by a single work item.	registers and local memory

# **OpenCL Context**

- Contains one or more devices
- OpenCL device memory objects are associated with a context, not a specific device





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Module 20 - Related Programming Models: OpenCL

Lecture 20.3 - OpenCL Host Code

### Objective

- To learn to write OpenCL host code
  - Create OpenCL context
  - Create work queues for task parallelism
  - Device memory Allocation
  - Kernel compilation
  - Kernel launch
  - Host-device data copy

### **OpenCL Context**

- Contains one or more devices
- OpenCL memory objects are associated with a context, not a specific device
- clCreateBuffer() is the main data object allocation function
  - error if an allocation is too large for any device in the context
- Each device needs its own work queue(s)
- Memory copy transfers are associated with a command queue (thus a specific device)

# OpenCL Context Setup Code (simple)

```
cl int clerr = CL SUCCESS;
cl context clctx = clCreateContextFromType(0, CL DEVICE TYPE ALL, NULL,
NULL, &clerr);
size t parmsz;
clerr = clGetContextInfo(clctx, CL CONTEXT DEVICES, 0, NULL, &parmsz);
cl device id* cldevs = (cl device id *) malloc(parmsz);
clerr = clGetContextInfo(clctx, CL CONTEXT DEVICES, parmsz, cldevs,
NULL);
cl command queue clcmdq = clCreateCommandQueue(clctx, cldevs[0], 0,
&clerr);
                          Where commands
                              will be sent.
```

### OpenCL Kernel Compilation: vadd

OpenCL kernel source code as a big string

```
const char* vaddsrc =
    "__kernel void vadd( global float *d_A, __global float *d_B,
    __global float *d_C, int N) { \n" [...etc and so forth...]

Gives raw source code string(s) to OpenCL
cl_program clpgm;
clpgm = clCreateProgramWithSource(clctx, 1, &vaddsrc, NULL,
&clerr);

Set compiler flags, compile source, and
retrieve a handle to the "vadd" kernel
sprintf(clcompileflags, \lambda -cl-mad-enable");
clerr = clBuildProgram(clpgm, 0, NULL, clcompileflags, NULL,
NULL);
cl_kernel clkern = clCreateKernel(clpgm, "vadd", &clerr);
```

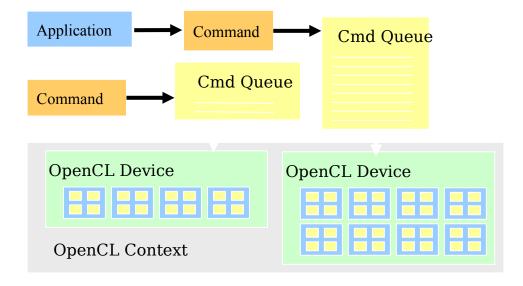
# **OpenCL Device Memory Allocation**

- clCreateBuffer();
  - Allocates object in the device Global Memory
  - Returns a pointer to the object
  - Requires five parameters
    - OpenCL context pointer
    - Flags for access type by device (read/write, etc.)
    - Size of allocated object
    - Host memory pointer, if used in copy-from-host mode
    - Error code
- clReleaseMemObject()
  - Frees object
    - Pointer to freed object

#### OpenCL Device Memory Allocation (cont.)

- Code example:
  - Allocate a 1024 single precision float array
  - Attach the allocated storage to d\_a
  - "d\_" is often used to indicate a device data structure

# **OpenCL Device Command Execution**



### OpenCL Host-to-Device Data Transfer

- clEnqueueWriteBuffer();
  - Memory data transfer to device
  - Requires nine parameters
    - OpenCL command queue pointer
    - Destination OpenCL memory buffer
    - Blocking flag
    - Offset in bytes
    - Size (in bytes) of written data
    - Source host memory pointer
    - List of events to be completed before execution of this command
    - Event object tied to this command

### OpenCL Device-to-Host Data Transfer

- clEnqueueReadBuffer();
  - Memory data transfer to host
  - requires nine parameters
    - OpenCL command queue pointer
    - Source OpenCL memory buffer
    - Blocking flag
    - Offset in bytes
    - Size of bytes of read data
    - Destination host memory pointer
    - List of events to be completed before execution of this command
    - Event object tied to this command

# OpenCL Host-Device Data Transfer (cont.)

- Code example:
  - Transfer a 64 \* 64 single precision float array
  - a is in host memory and d\_a is in device memory

# OpenCL Host-Device Data Transfer (cont.)

- clCreateBuffer and clEnqueueWriteBuffer can be combined into a single command using special flags.
- Eg:
- d A=clCreateBuffer(clctxt,
- CL\_MEM\_READ\_ONLY | CL\_MEM\_COPY\_HOST\_PTR, mem\_size, h\_A, NULL);
  - Combination of 2 flags here. CL\_MEM\_COPY\_HOST\_PTR to be used only if a valid host pointer is specified.
  - This creates a memory buffer on the device, and copies data from h\_A into d\_A.
  - Includes an implicit clEnqueueWriteBuffer operation, for all devices/command queues tied to the context clctxt.

#### Device Memory Allocation and Data Transfer for vadd

```
float *h A = ..., *h B = ...;
   // allocate device (GPU) memory
  cl mem d A, d B, d C;
  d A = clCreateBuffer(clctx, CL MEM READ ONLY |
          CL MEM COPY HOST PTR, N *sizeof(float), h A, NULL);
  d B = clCreateBuffer(clctx, CL MEM READ ONLY |
          CL MEM COPY HOST PTR, N *sizeof(float), h B, NULL);
  d C = clCreateBuffer(clctx, CL MEM WRITE ONLY,
    N *sizeof(float), NULL, NULL);
```

#### Device Kernel Configuration Setting for vadd

```
clkern=clCreateKernel(clpgm, "vadd", NULL);
clerr= clSetKernelArg(clkern, 0, sizeof(cl mem), (void *)&d A);
clerr= clSetKernelArg(clkern, 1, sizeof(cl mem), (void *)&d B);
clerr= clSetKernelArg(clkern, 2, sizeof(cl mem), (void *)&d C);
clerr= clSetKernelArg(clkern, 3, sizeof(int), &N);
```

#### Device Kernel Launch and Remaining Code for vadd



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